

# CASA

VLBI

# WORKSHOP 2020

2-6 NOVEMBER 2020

## 10. WIDE-FIELD IMAGING

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# Outline

1. Motivation i.e. why do we want to image degrees of the sky with VLBI?
2. Challenges
3. Calibrating wide-field VLBI data\*
  - a. Phase referencing
  - b. Self-calibration
  - c. Primary beam correction
4. Conclusions / take-away points

\*In particular, highlight the nuances between standard calibration and wide field + how techniques developed for wide-field VLBI can be applicable to standard VLBI observing!



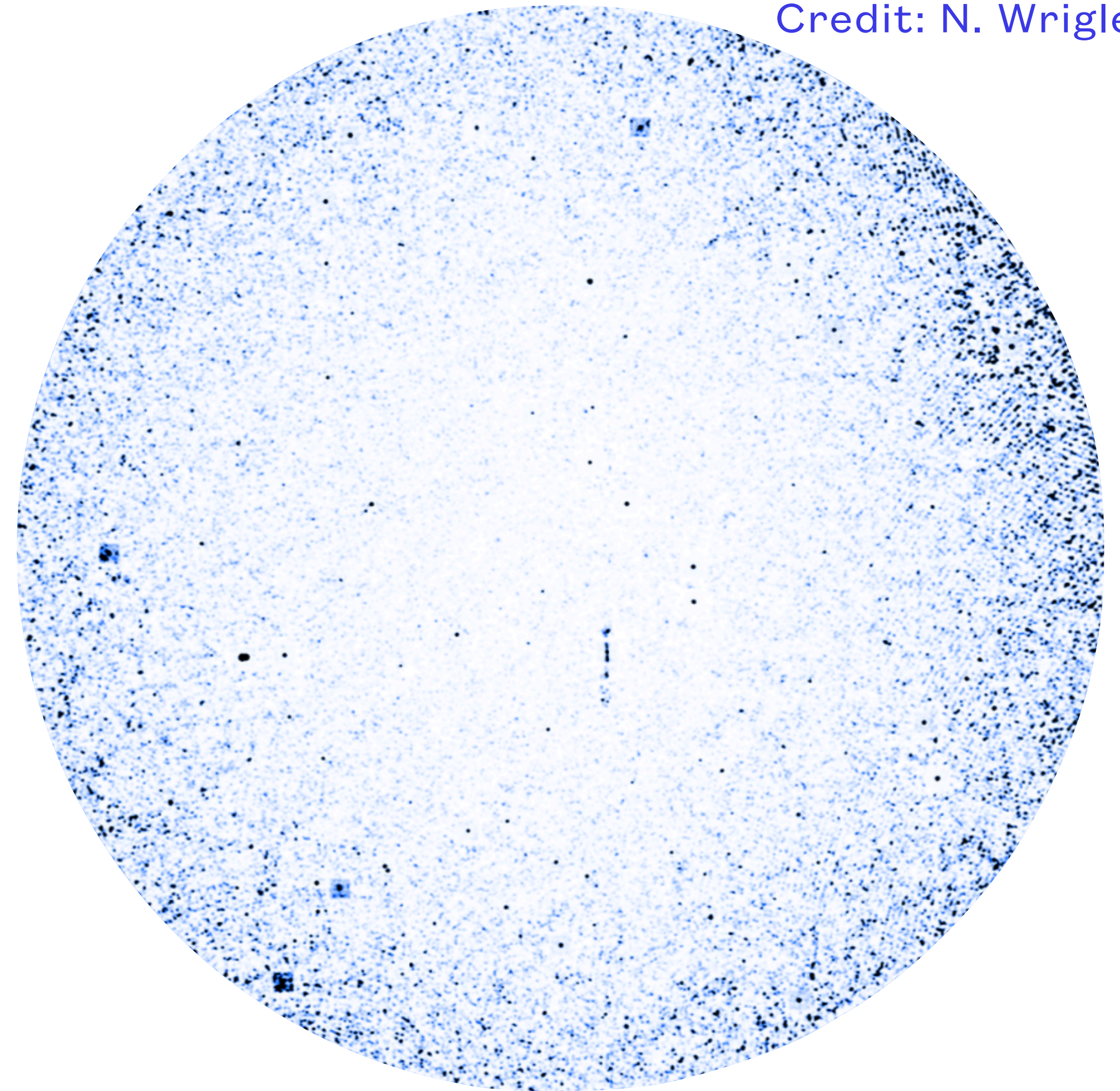
# Wide-field VLBI - definition

### ***What do we mean by wide-field VLBI?***

- Simply concerned with *imaging the entire primary beam of a VLBI array*
- See multiple science targets in one observations
- Historically, much easier for shorter baseline instruments

*What are the advantages of imaging the entire primary beam?*

Credit: N. Wrigley

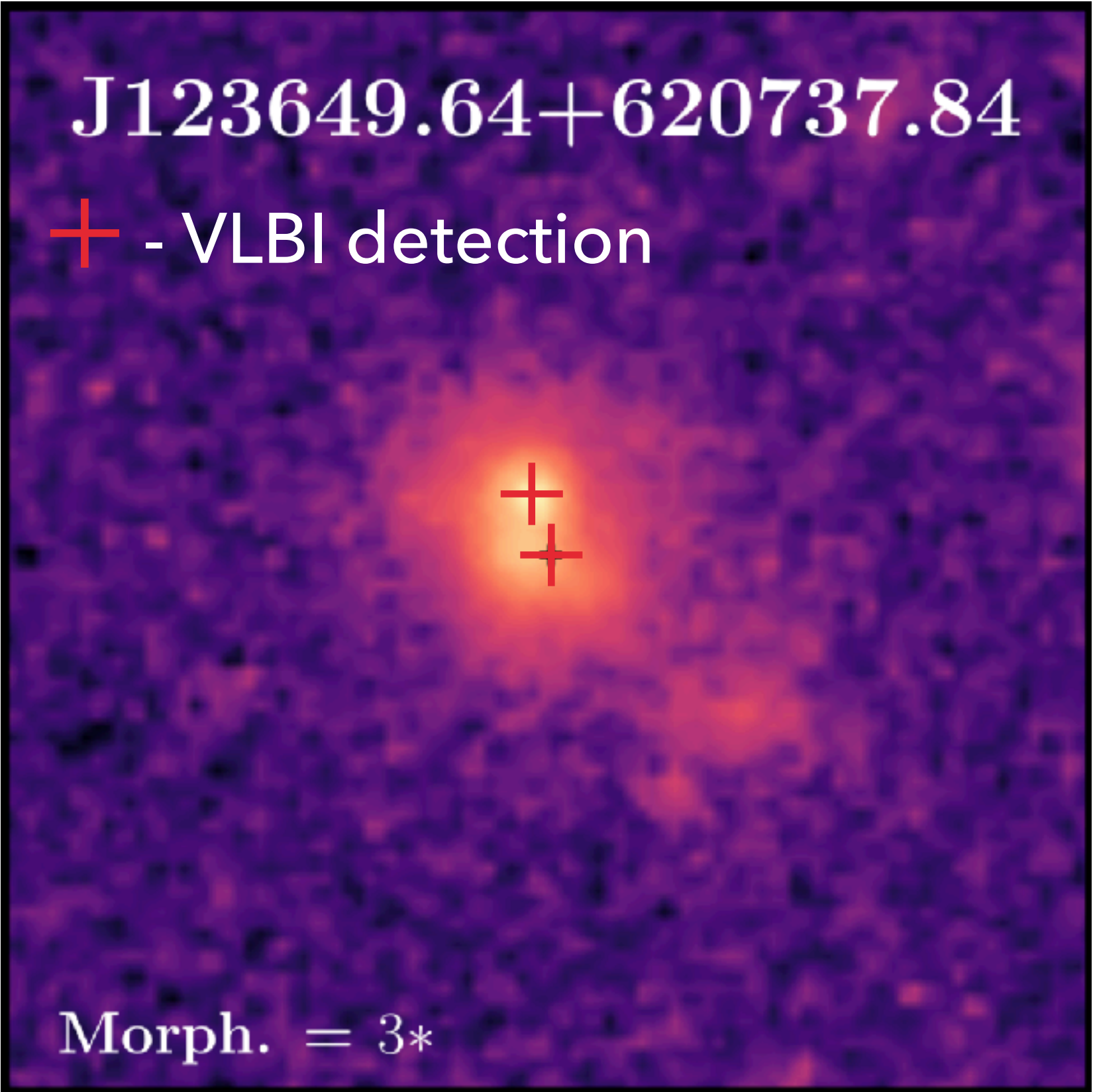
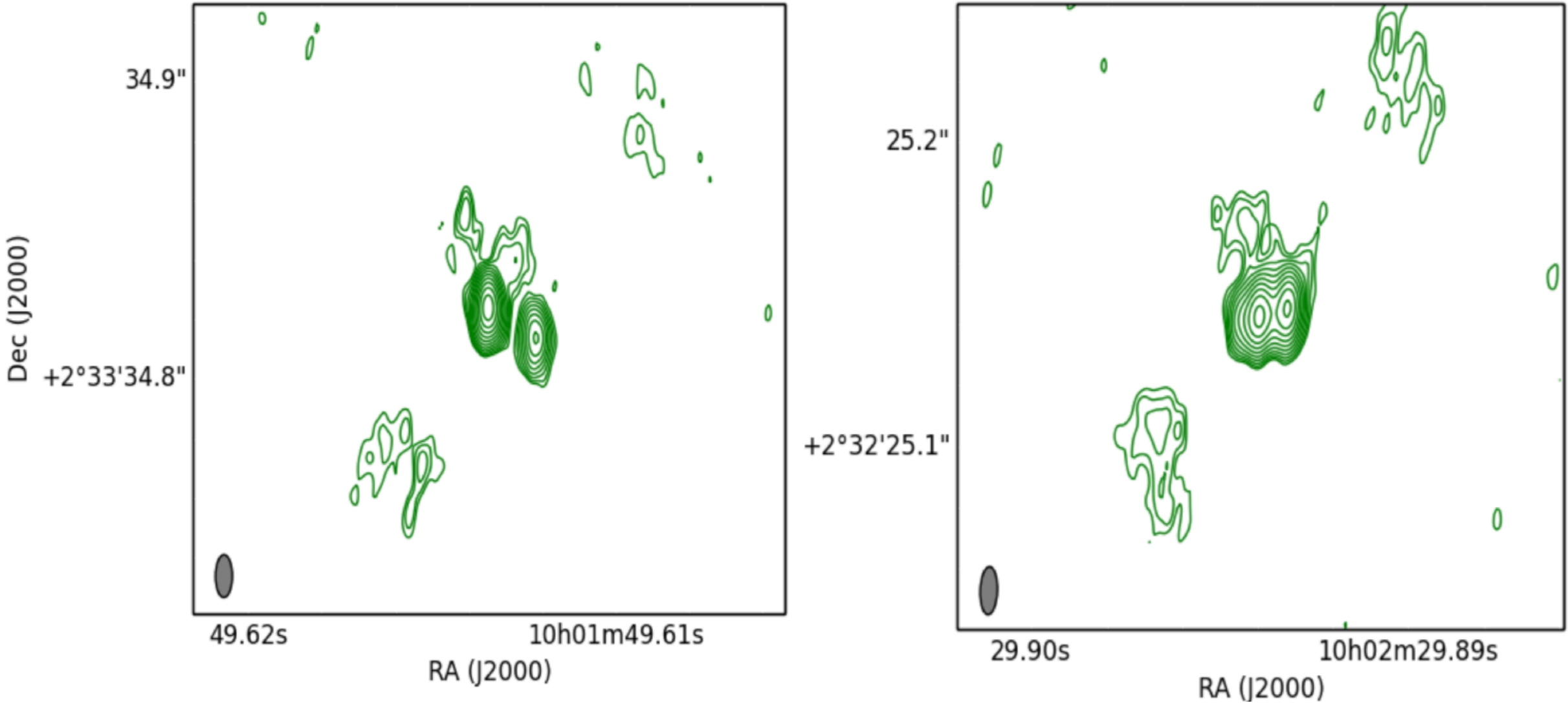


Primary beam corrected  
JVLA+MERLIN image of the GOODS-N field

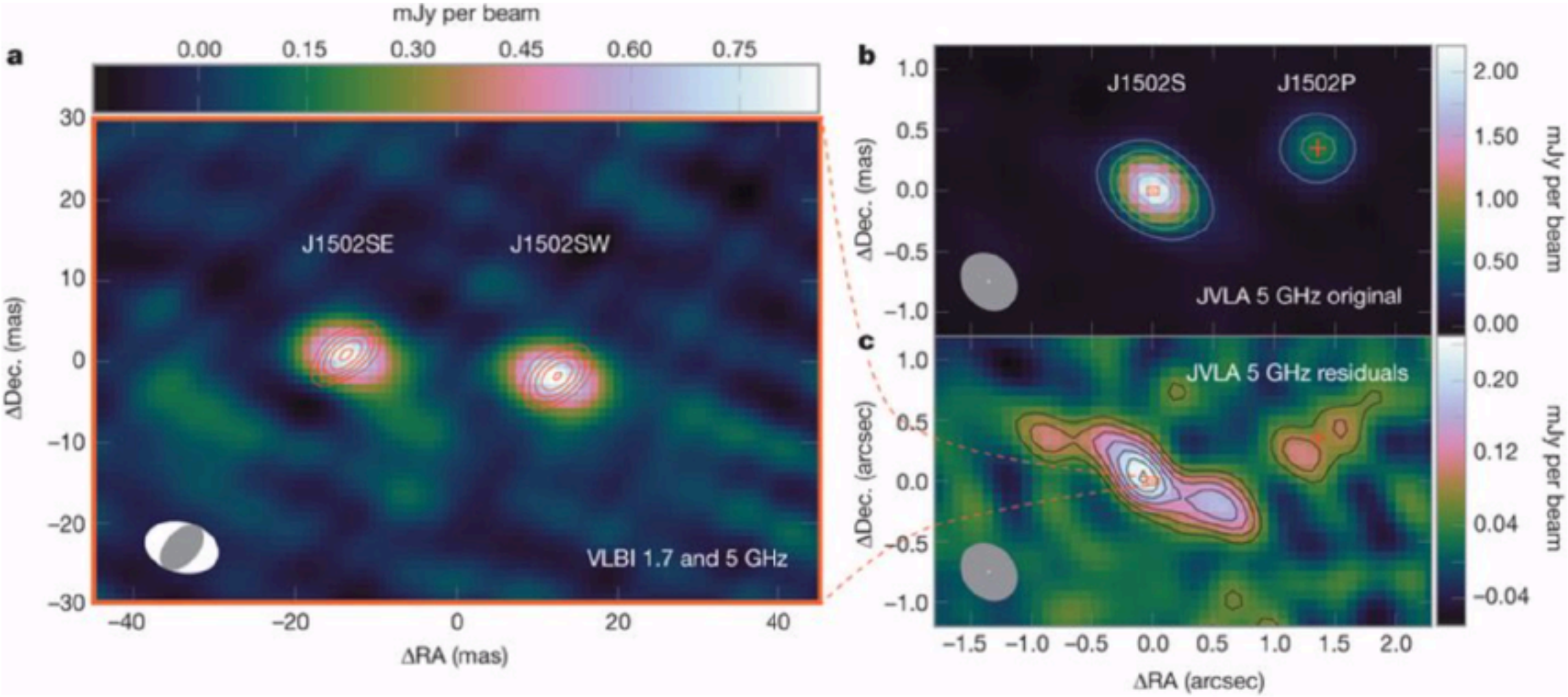


# Some science examples - supermassive black hole binaries

Herrera-Ruiz+17



Radcliffe+ in prep.

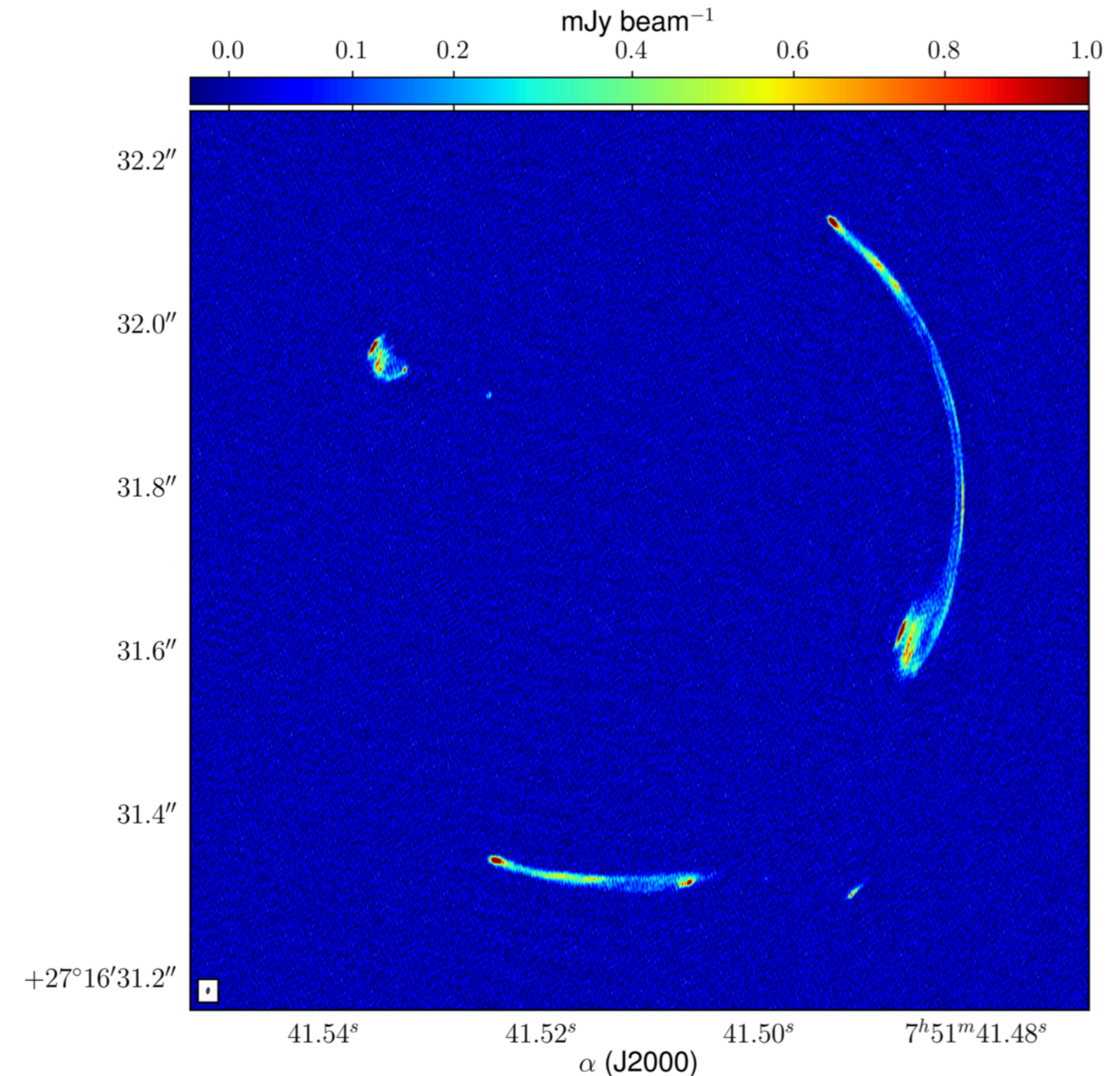


Deane+14



# Gravitational lenses

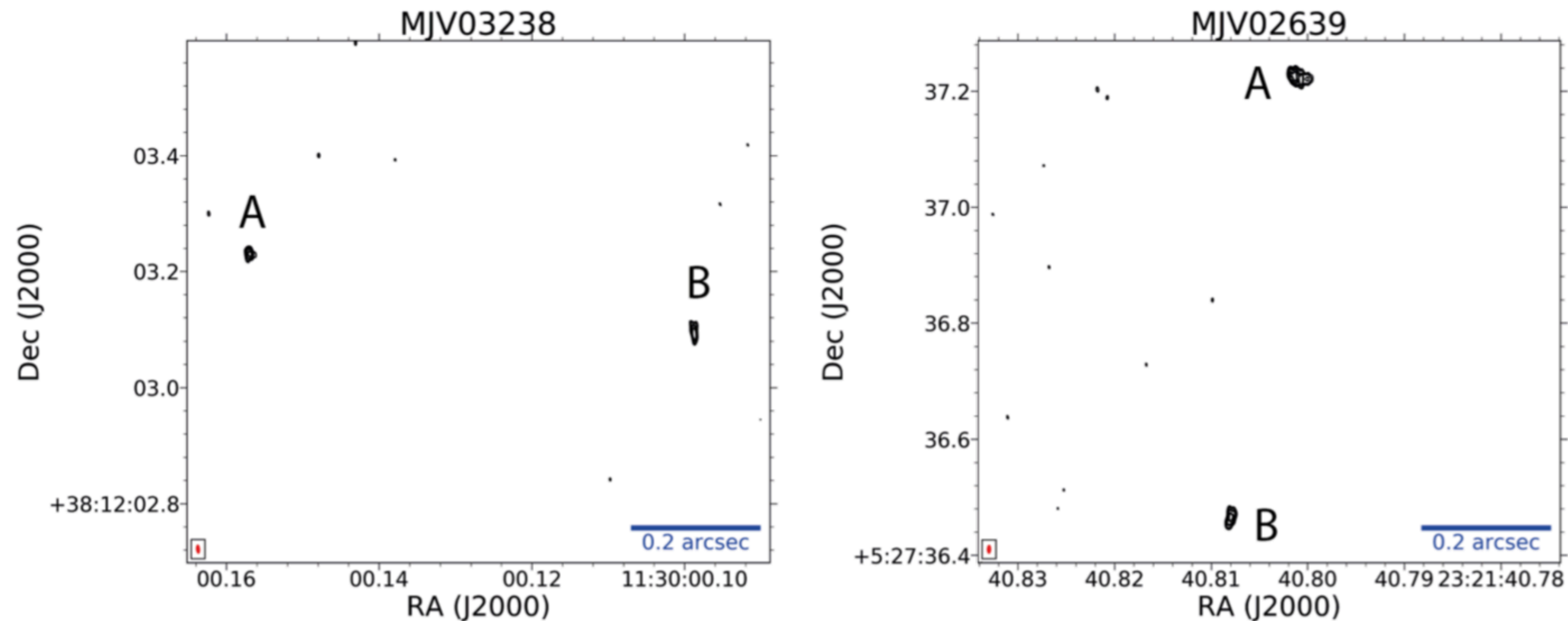
- Rare ( $\sim 0.3\%$  of VLBI sources)
- Independently measure the sub-structure mass-function within galaxies.
- Unique probing of the low-mass end of the dark matter halo mass-function
- High resolution of VLBI can constrain lens models





# Gravitational lenses

- Spingola+19 searched 3640 mJIVE-20 survey sources
- Found two gravitational lenses!

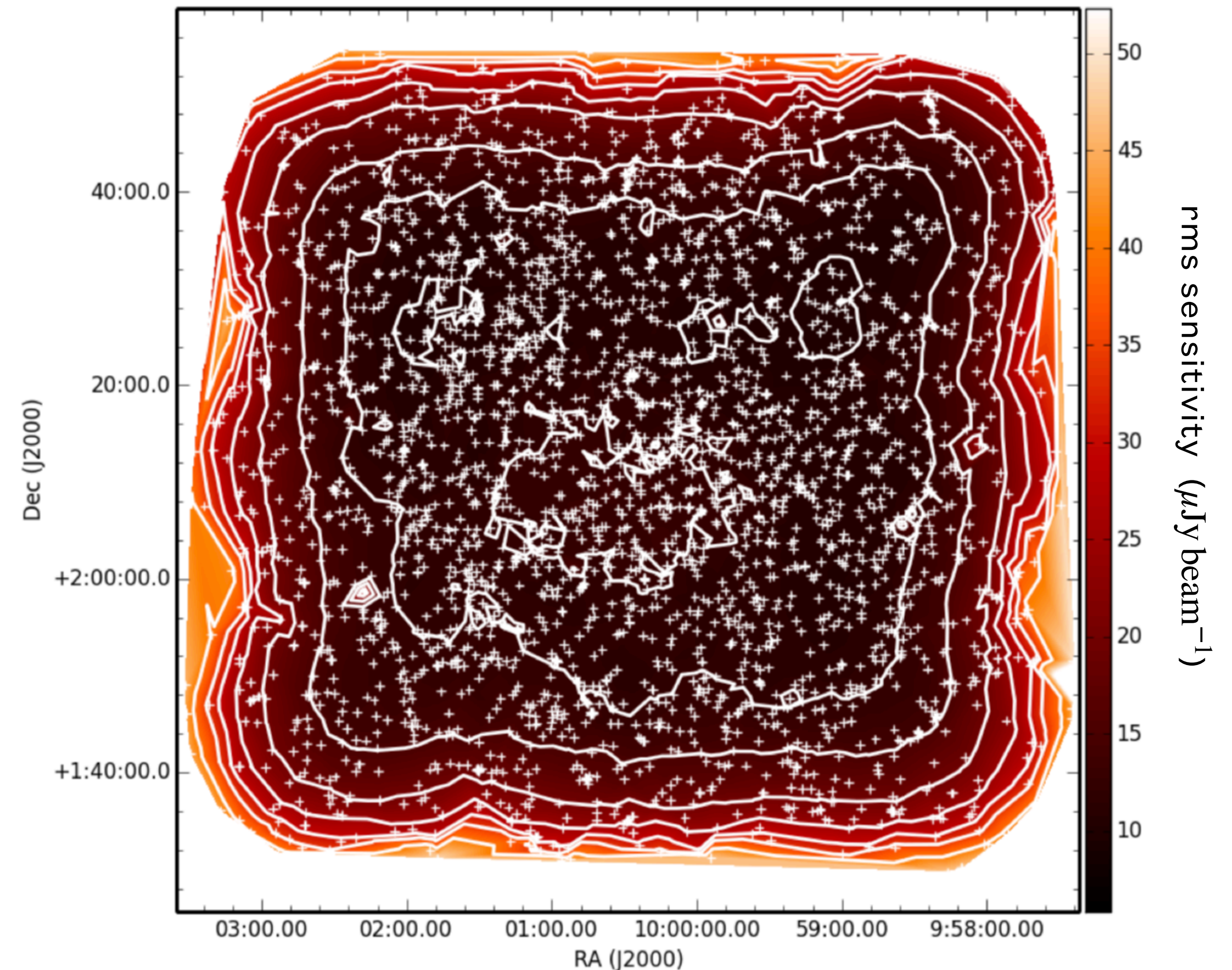




# AGN surveys

- VLBI detection sure indicator of AGN (high brightness temperatures  $> 10^5$  K)
- Use VLBI to understand nature of radio-mode AGN
- Other AGN identification methods are notably incomplete or contaminated.
- *Note - there are many more wide-field VLBI use-cases too (e.g. ISM of nearest galaxies; Morgan+13, supernovae; Radcliffe+19 etc.)!*

COSMOS-VLBA – 2 degree survey  
(Herrera-Ruiz+17, 18)

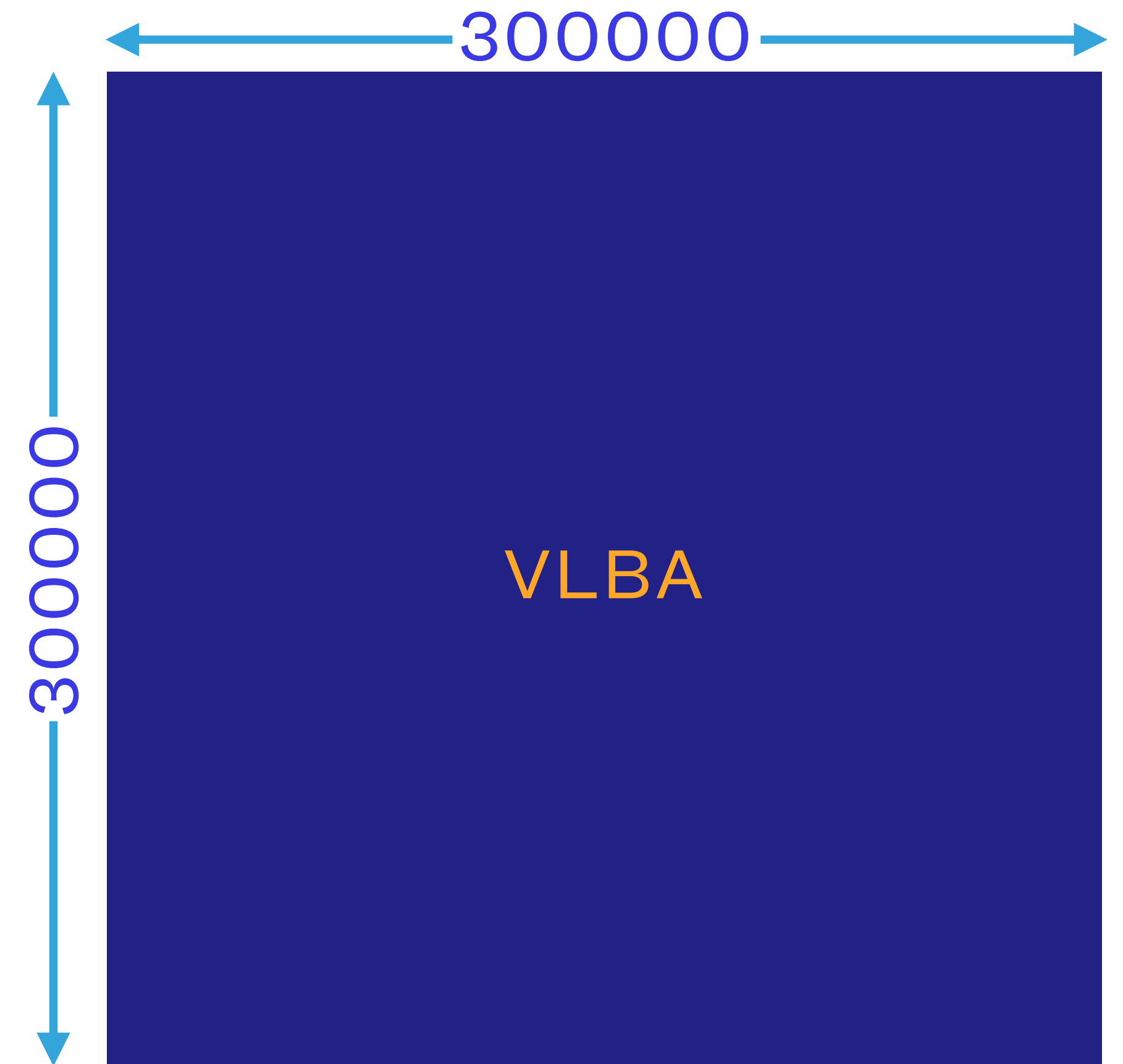
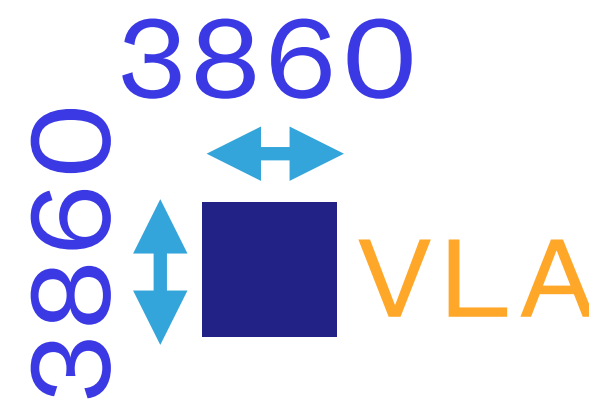




# Imaging the entire primary beam - challenges

## 1. Image sizes

- Assuming ~0.5 degree field-of-view (25m telescopes at 1.4 GHz) w/ Nyquist sampling
- *Very Large Array* (VLA) A-configuration (1.4'' resolution) -  $\sim 1.4 \times 10^7$  pixels
- *Very Long Baseline Array* (VLBA) - (~6 mas resolution) -  $\sim 1 \times 10^{11}$  pixels

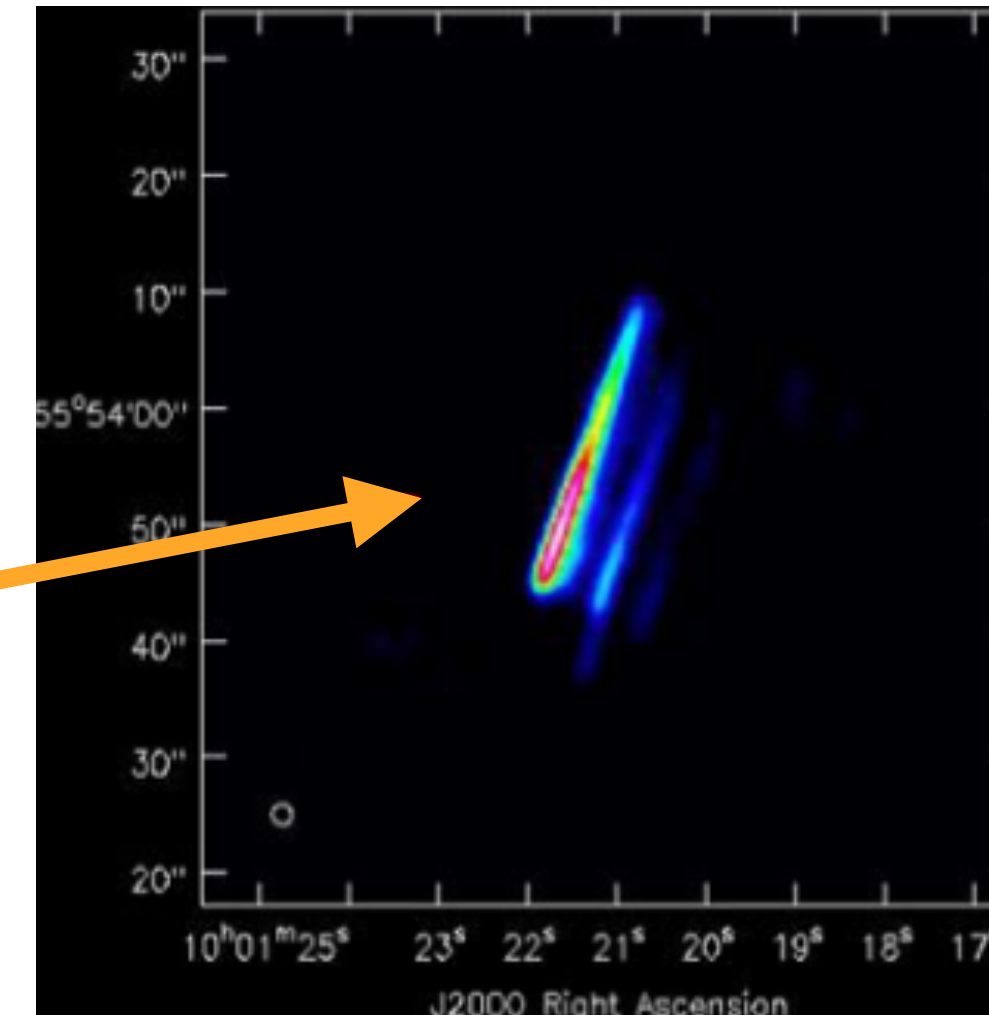
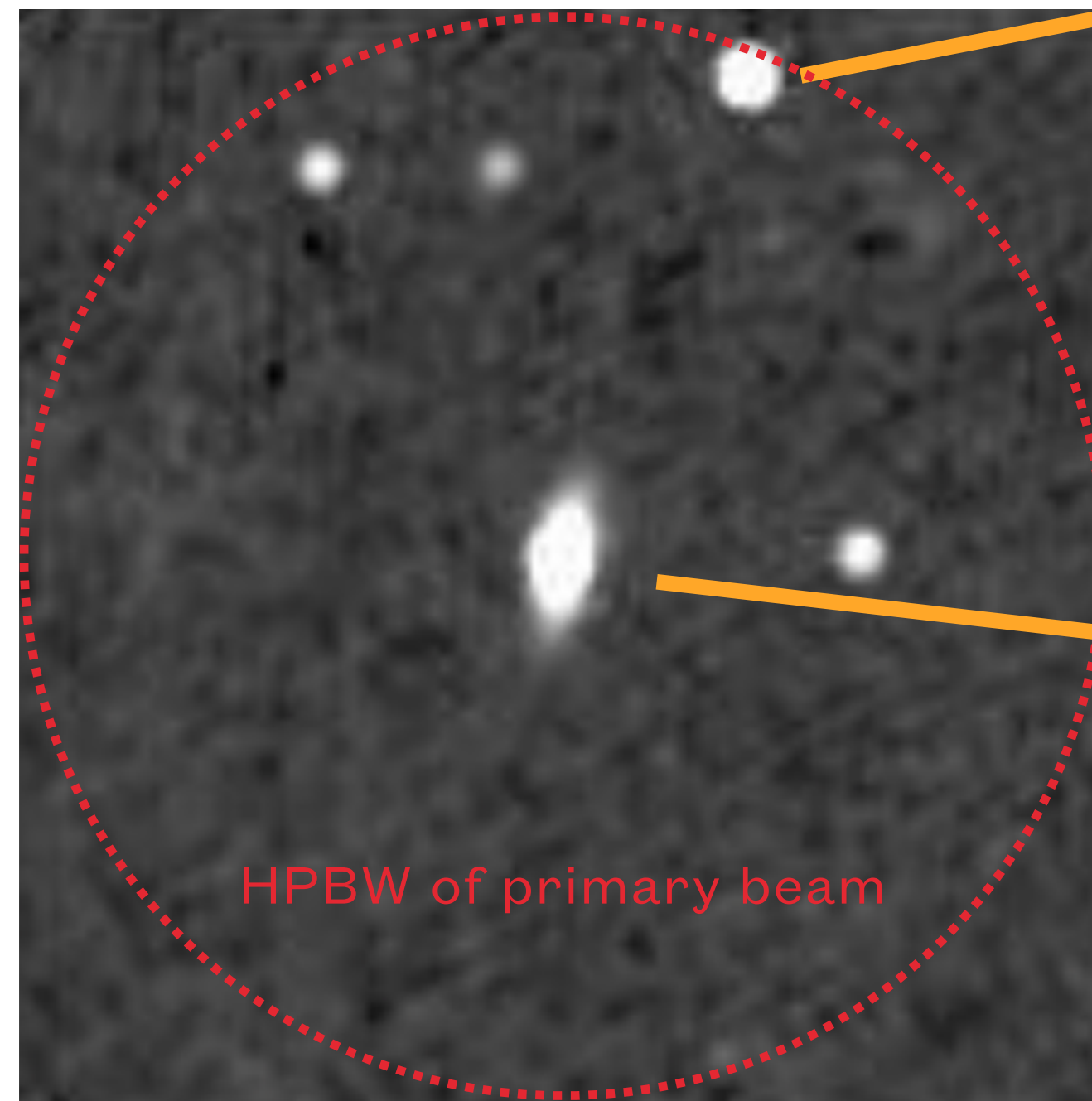




# Imaging the entire primary beam - challenges

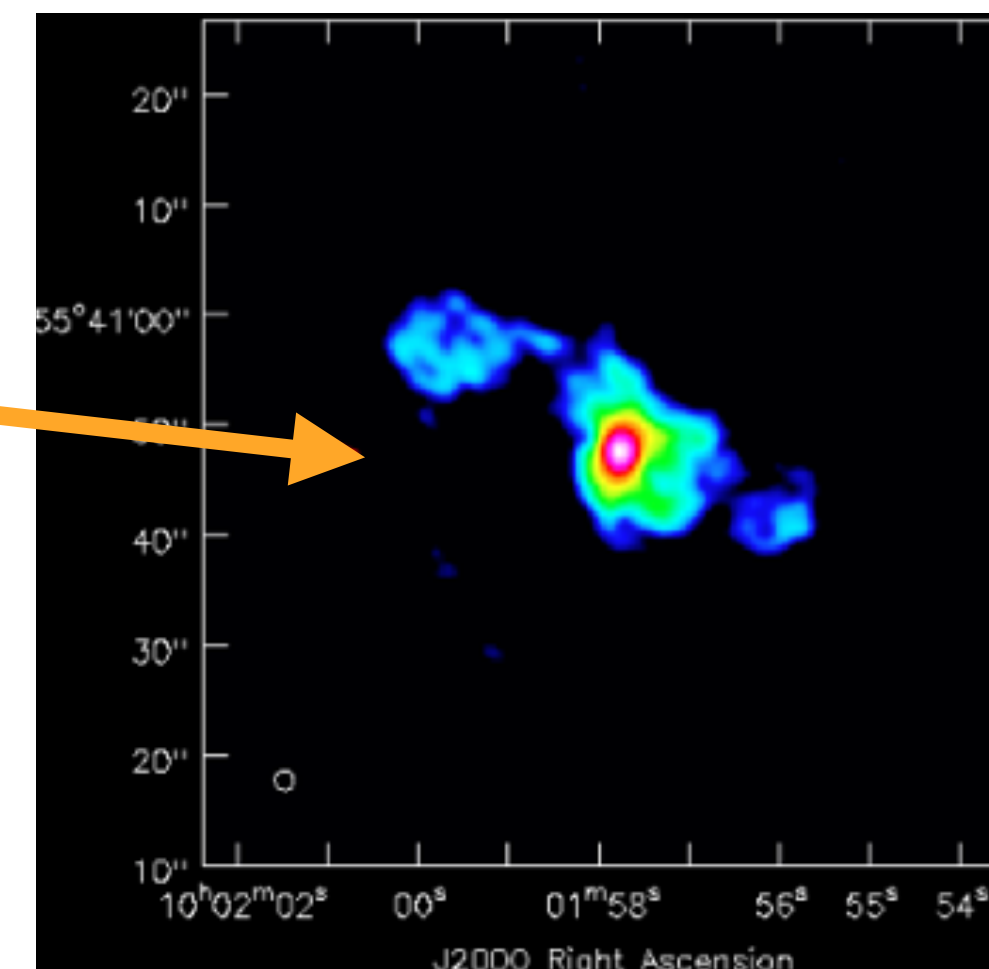
## 2. Smearing

*NVSS (VLA) - short baselines*



Edge of PB  
massively  
smeared

*e-MERLIN - long baselines*



Centre of PB  
no smearing

Image credit - T. Muxlow



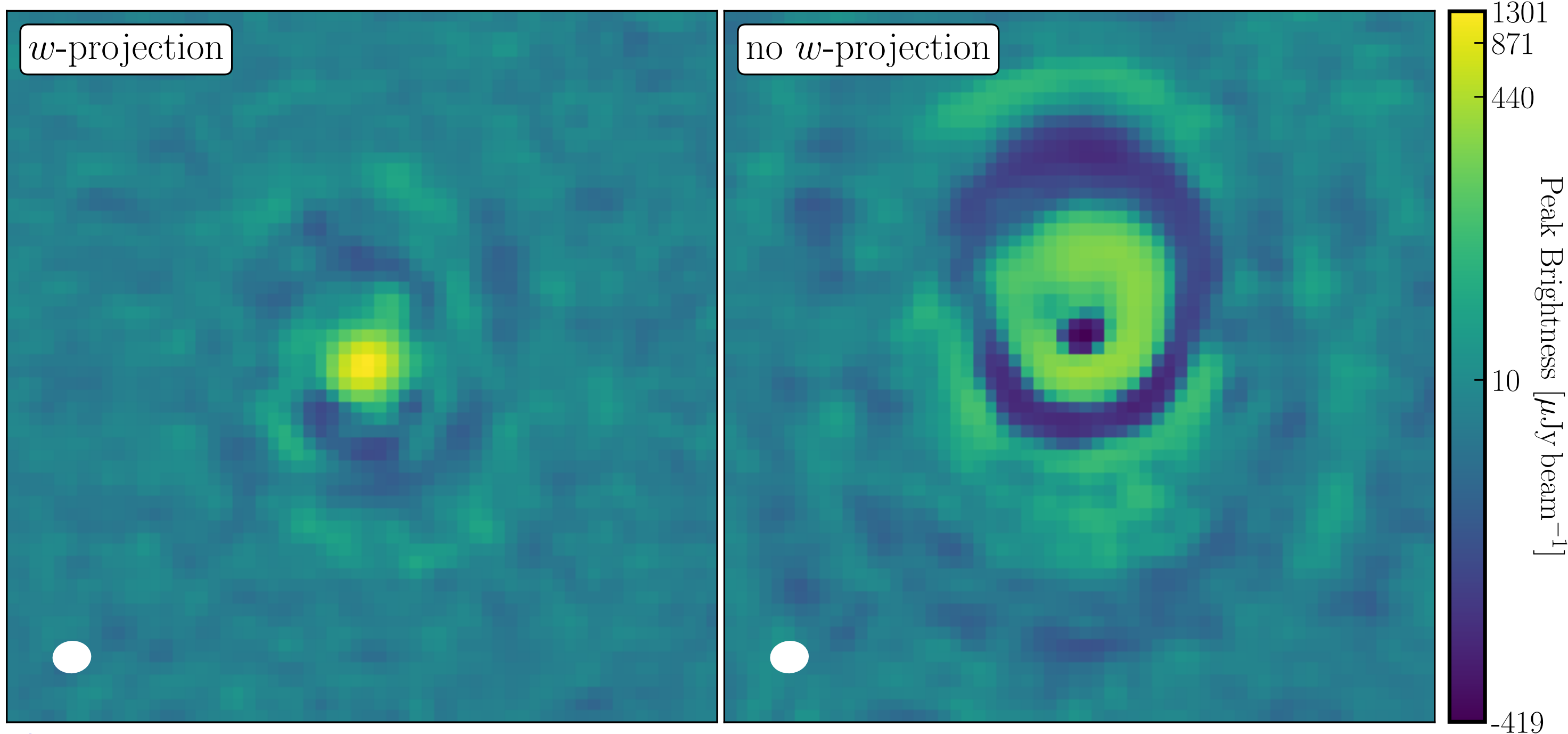
# Imaging the entire primary beam - challenges

## 3. Non-coplanarity or the $w$ term

Ideal RIME

$$V(u, v) = \iint_{lm} B(l, m) \exp \left\{ -2\pi i \left[ ul + vm + w(n-1) \right] \right\} \frac{dl dm}{n}$$

e-MERLIN - source 7.5' from pointing centre



\* computationally expensive

- The pesky extra term of:

$$\frac{1}{n} \exp \left[ w(n-1) \right] \quad * n = \sqrt{1 - l^2 - m^2}$$

stops us having a true 2D-FT

**Severity of these issues  $\propto$  baseline length & distance from phase centre**



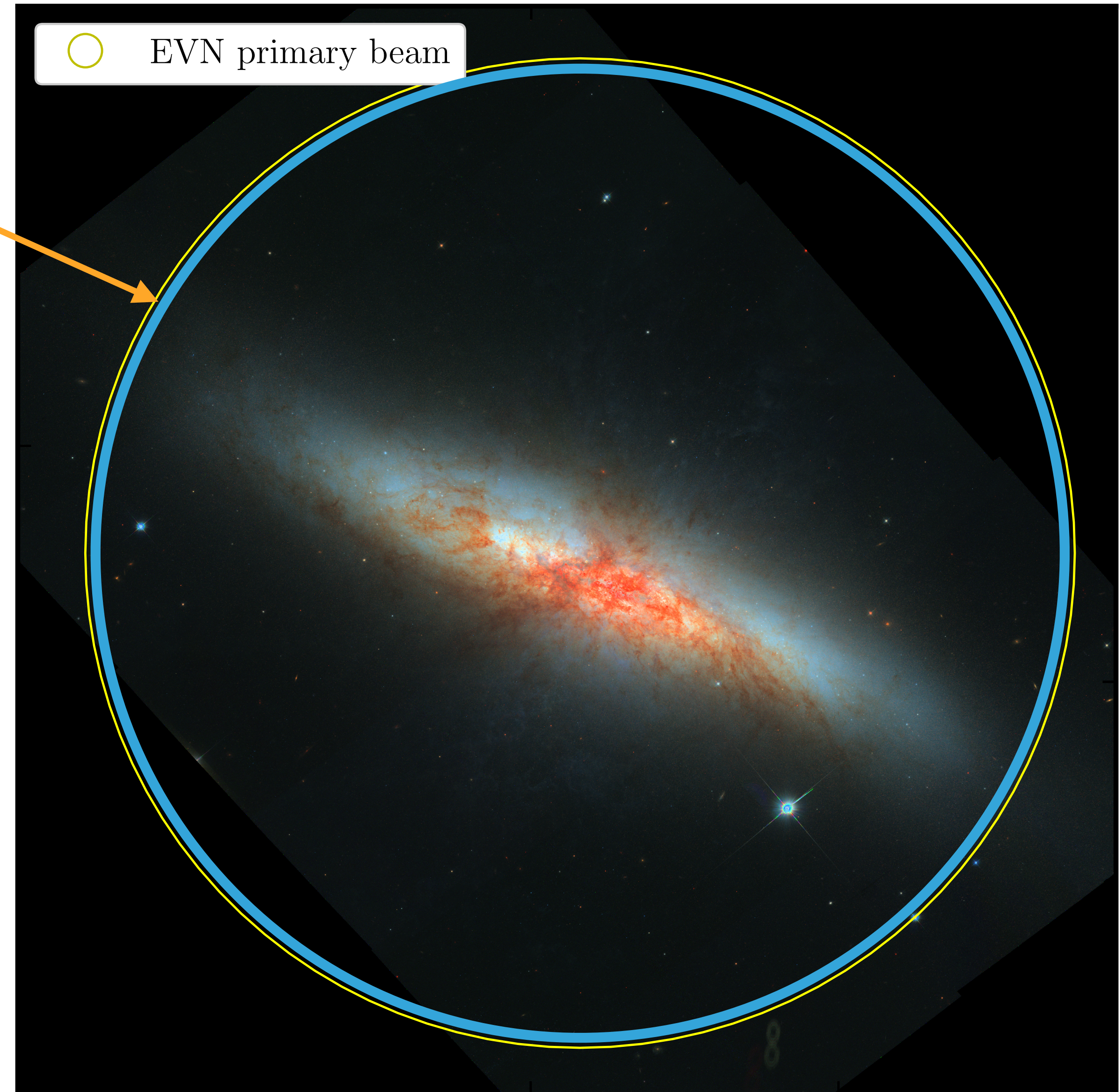
# Solutions - standard 'wide-field' correlation

- Correlate at high temporal & frequency resolution

*Result* - monolithic and huge data set which is 99.99999% noise

- This huge single data set is often TBs\* in size
- Often have to shift to different positions in the primary beam which is inaccurate using standard software.

Field-of-view due  
to smearing



\*Note: a 22 telescope, 12 hour EVN observation @ 1 Gbps > 15 TB

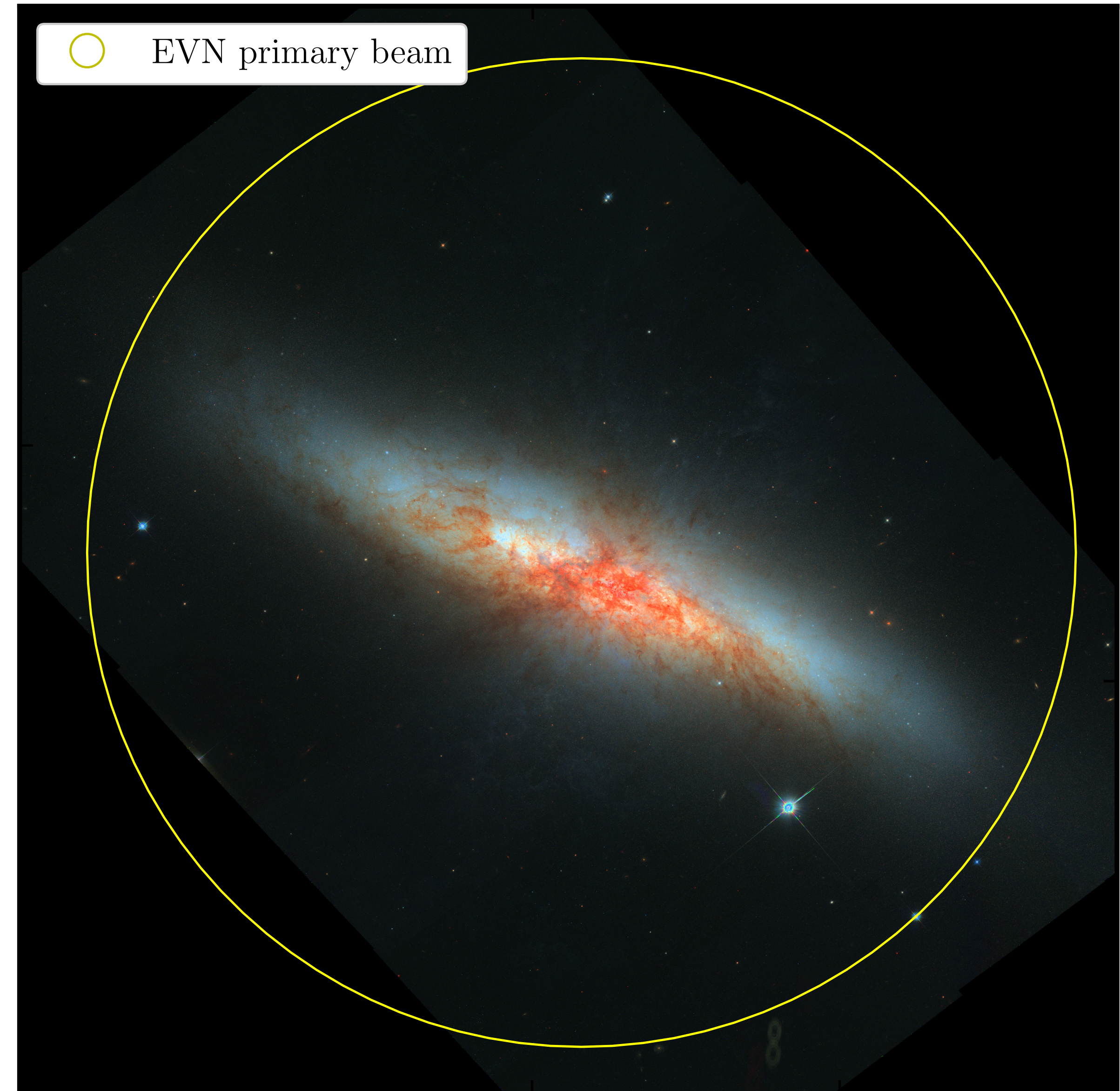


# Multiple phase-centre correlation

1. Split data into time chunks
2. Correlate each chunk at very high time & frequency resolution to prevent smearing
3. Copies & phase shift to multiple locations in primary beam
4. Average in time & frequency

*Result* - you receive lots of small (in FoV and size) *data sets at different positions* across the primary beam so it's easily parallelisable!

- Choice of phase centres is up to the user and could cover entire primary beam, or just some known sources of interest e.g. VLA positions etc.



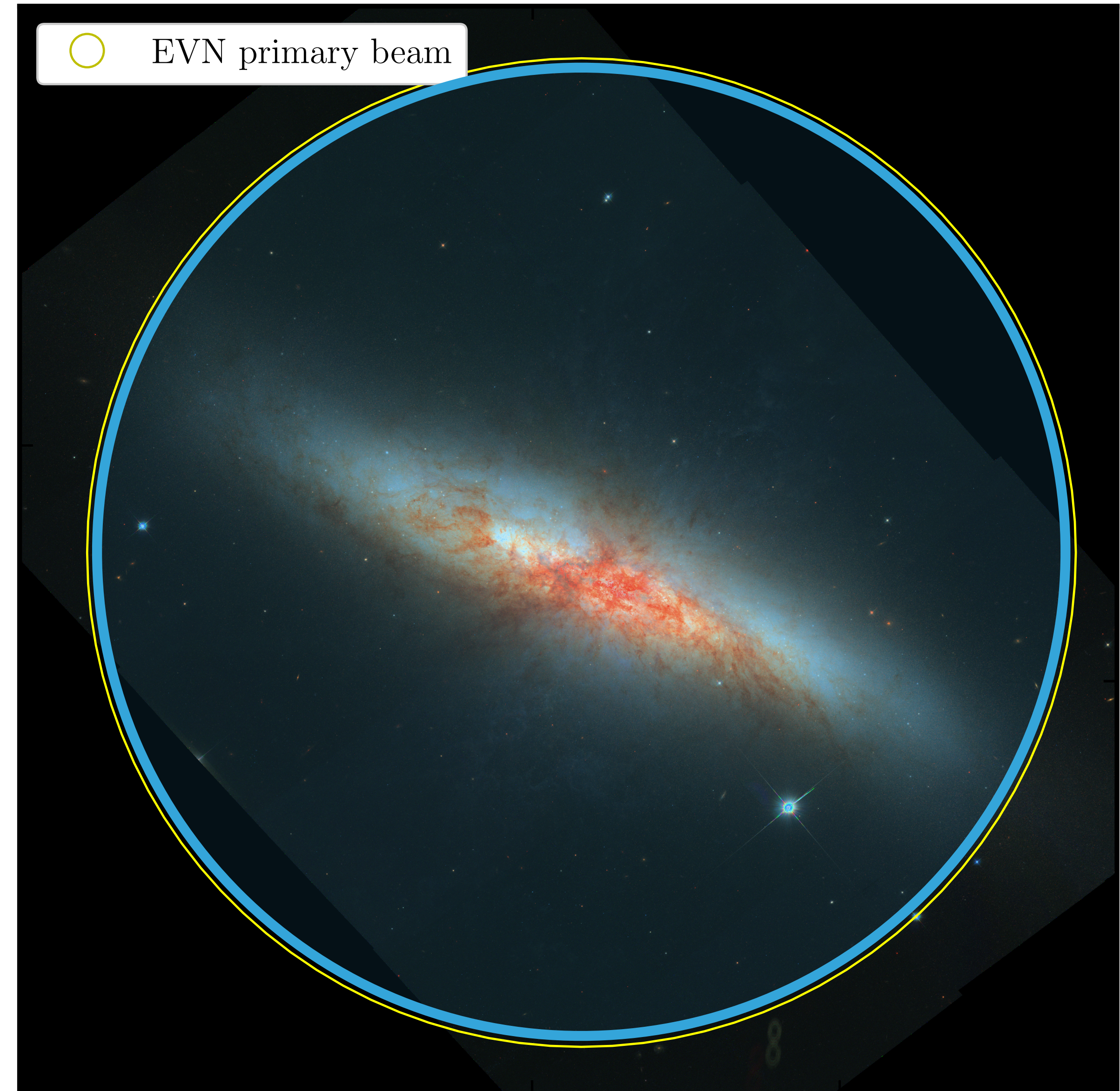


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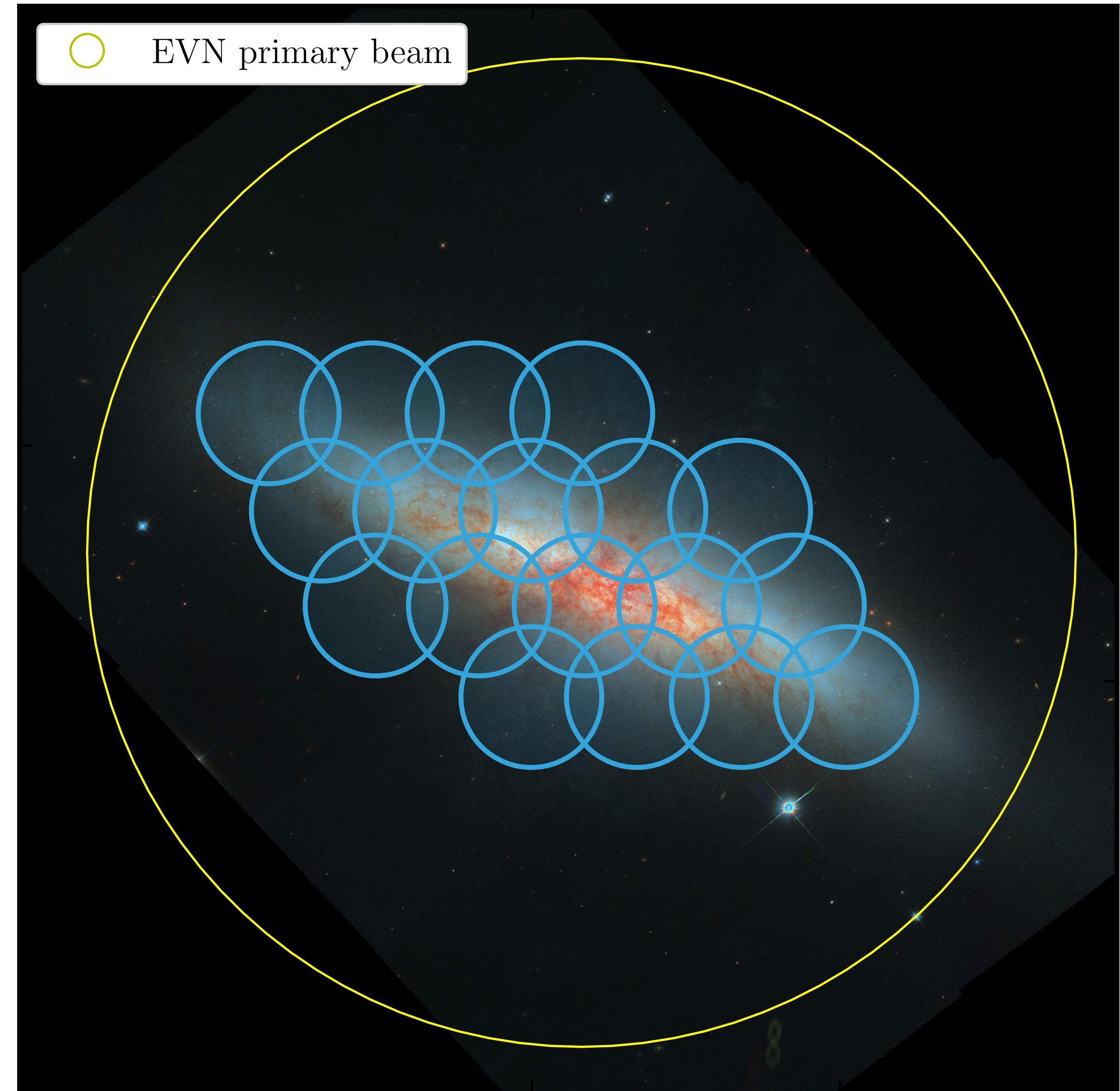


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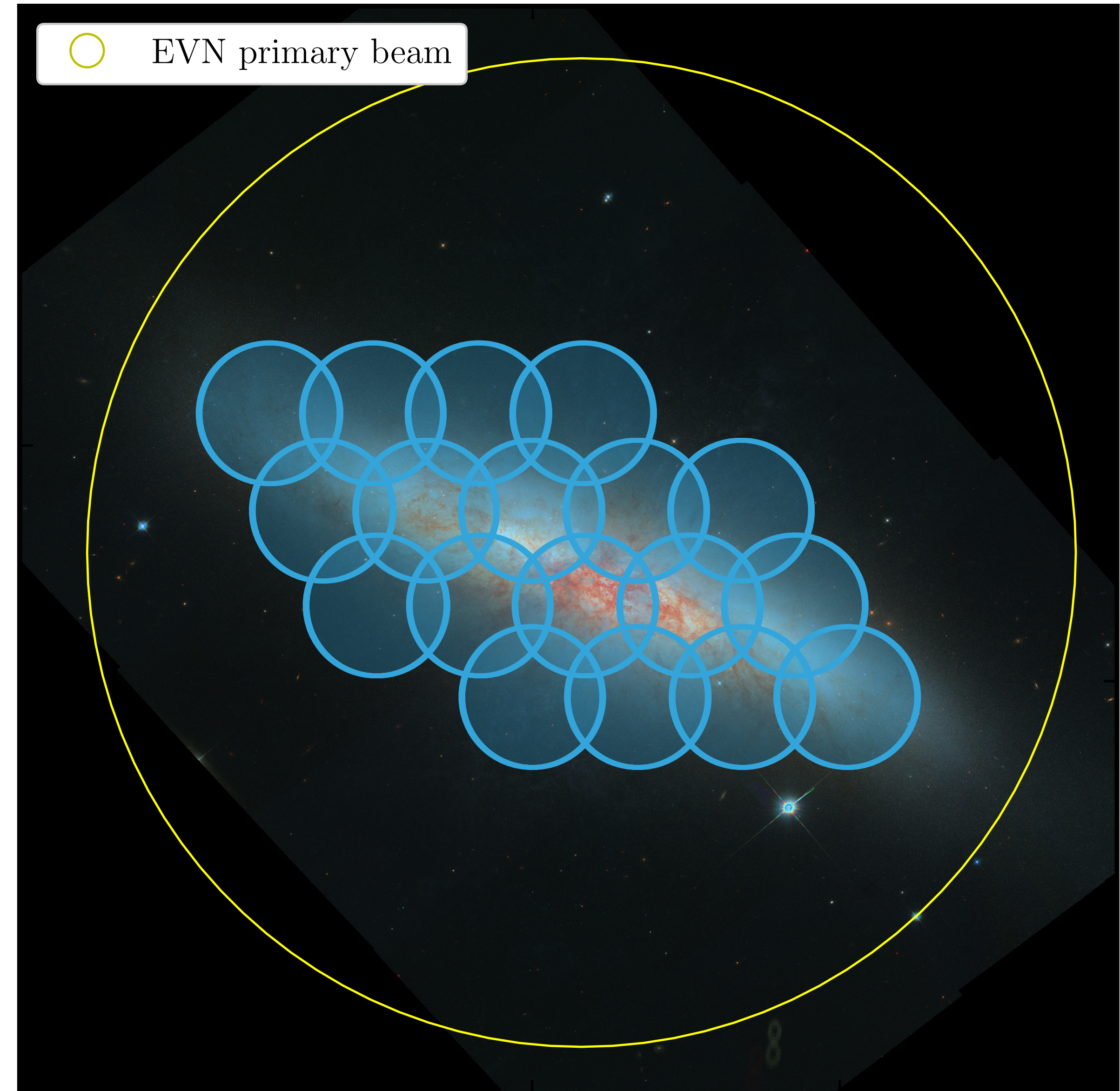


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# Calibrating wide-field VLBI data

- Calibrating wide-field VLBI data is much easier than you'd think. There are three areas that are different from standard VLBI data processing,
  - a. Applying solutions in phase referencing
  - b. Self-calibration
  - c. Primary beam corrections
- In addition, there are many pipelines that have been developed (e.g. rPICARD, Janssen+19), or in development (e.g. cm-VLBI pipeline & EVN CASA pipeline), that can make standard calibration much easier.



# A shameless plug - the cm-VLBI pipeline

- cm-VLBI pipeline based in CASA (v5.7+/6.1+) currently in development (current v0.8) - [https://github.com/jradcliffe5/VLBI\\_pipeline](https://github.com/jradcliffe5/VLBI_pipeline) - **it needs some testers please :)**! Nb. it's modular so works with other pipelines.
- Currently does the following,
  - A priori calibration for EVN & VLBA data (e.g.  $T_{\text{sys}}$ , gaincurves, ionospheric dispersive delays)
  - Fully parallelised a priori, flagging, phase referencing, and self-calibration via casampi (continuum only at the moment)
  - Support for use on HPC clusters controlled by SLURM / PBS Pro (+ usable on local machines)
  - Built for wide-field VLBI surveys, but direction-independent calibration works for normal data too.
- In development,
  - Primary beam correction schemes
  - Multi-source self-calibration (and direction dependent calibration too)
  - Parameter automation (e.g. source finding, calibration solution intervals etc.)

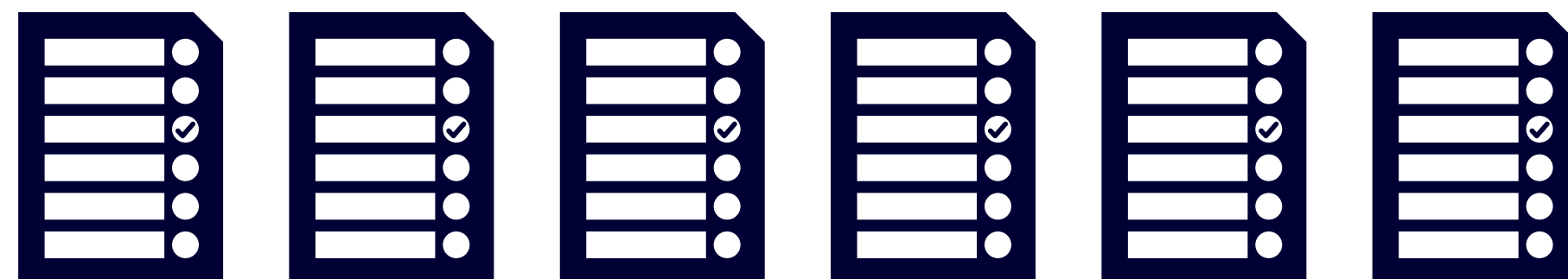


# Phase referencing



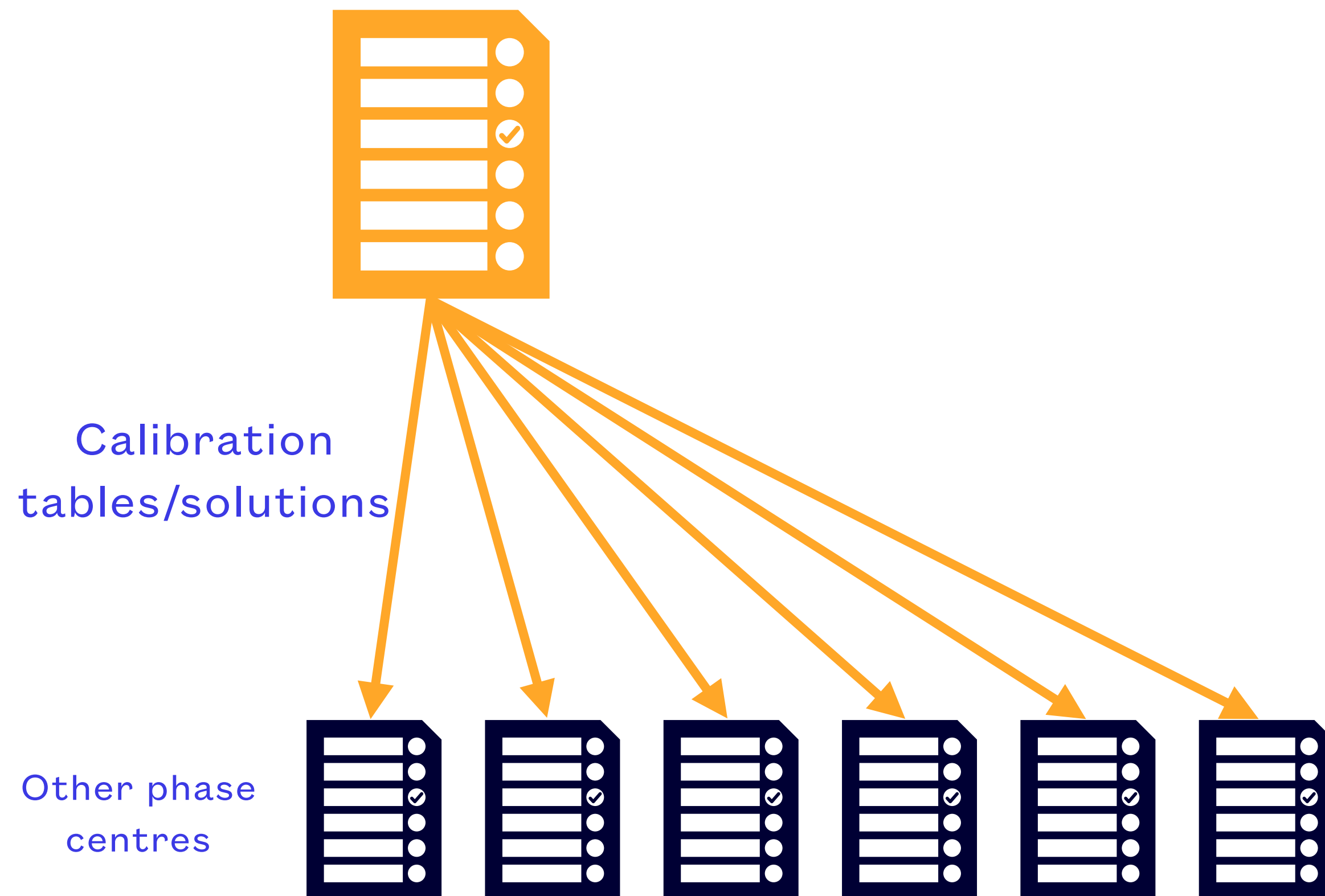
- Typically, one phase centre will contain the phase, bandpass and fringe finders sources.
- Most importantly - **standard VLBI calibration applies**
- Calibration tables & flagging tables derived can then be applied to ALL other target fields
- Easily parallelisable so calibration is very quick
- Parallelisation implemented using `casamp1` in cm-VLBI pipeline

Other phase  
centres





# Phase referencing

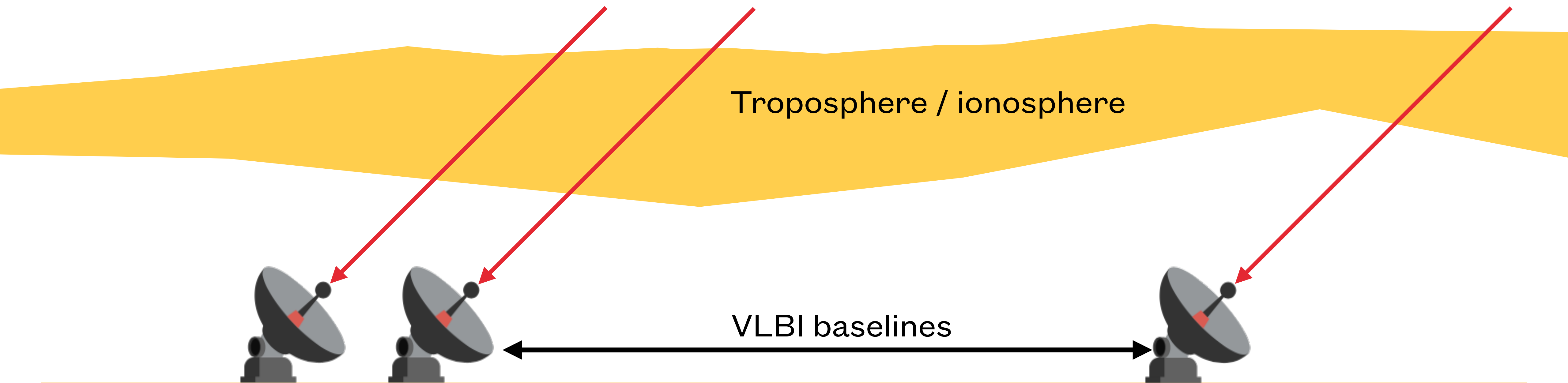


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# Self-calibrating VLBI data

- Atmospheric effects correlated on short baselines **but not** on longer baselines (>500 km)
- Often uncorrelated at different locations within target field too...
- Also, the number density of VLBI sources (and their flux densities) lower due to the 'resolving out' / spatial filtering effect.

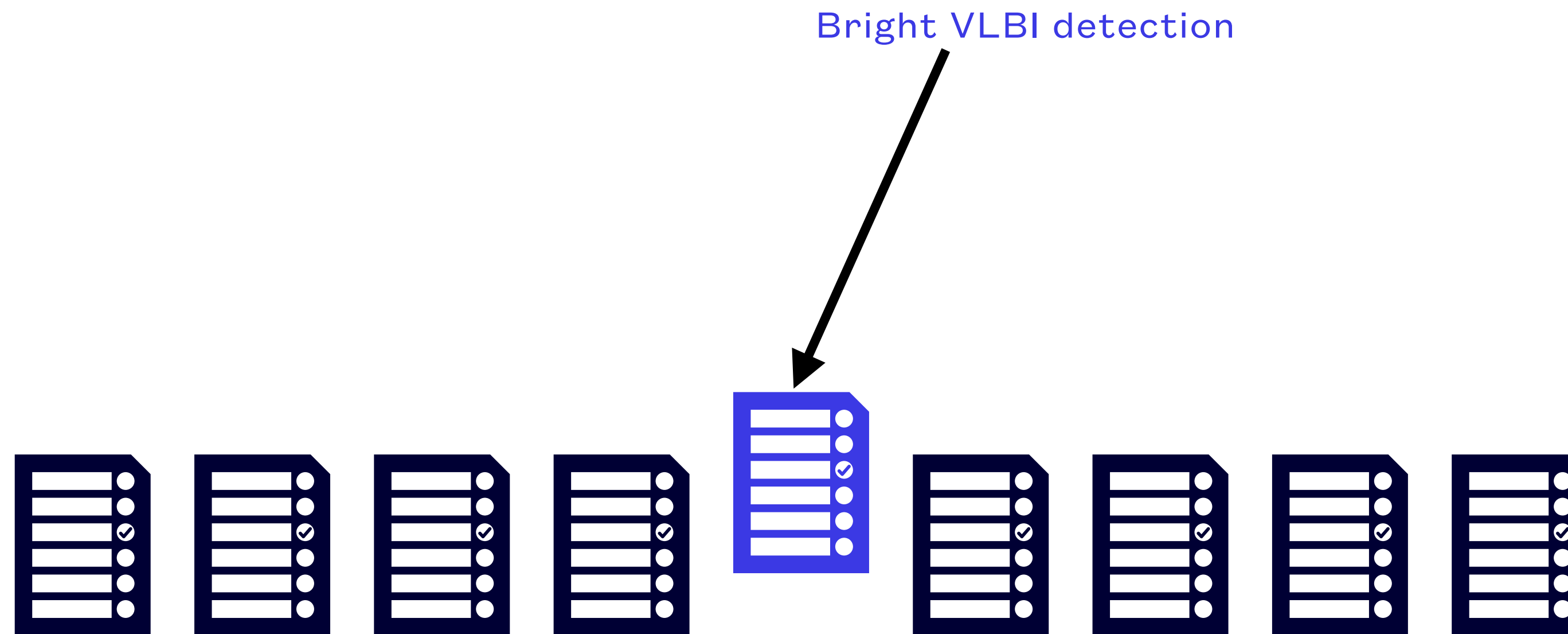




# Self-calibration solution 1

## In-beam phase referencing

- Put a phase-centre on a bright source within the target field and use this to derive self-calibration solutions.
- Then, apply solutions to all other phase centres.
- However, only some target fields have bright enough detections so...





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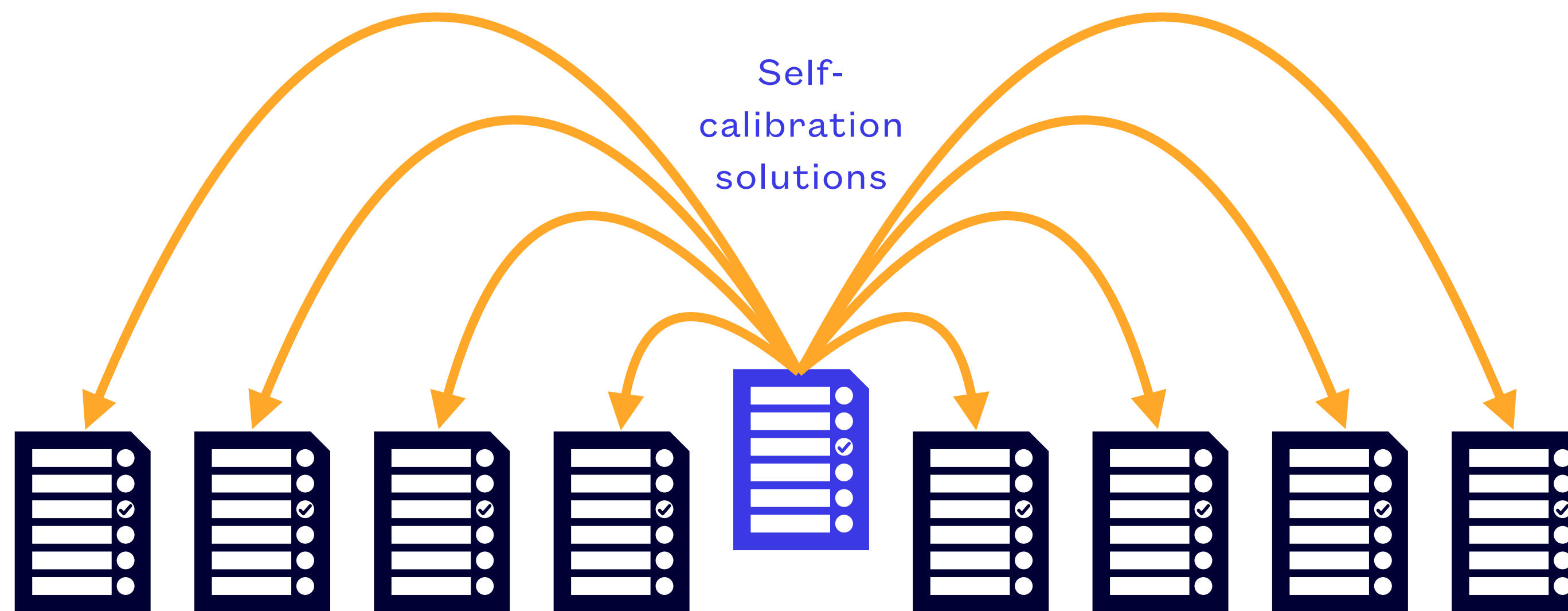




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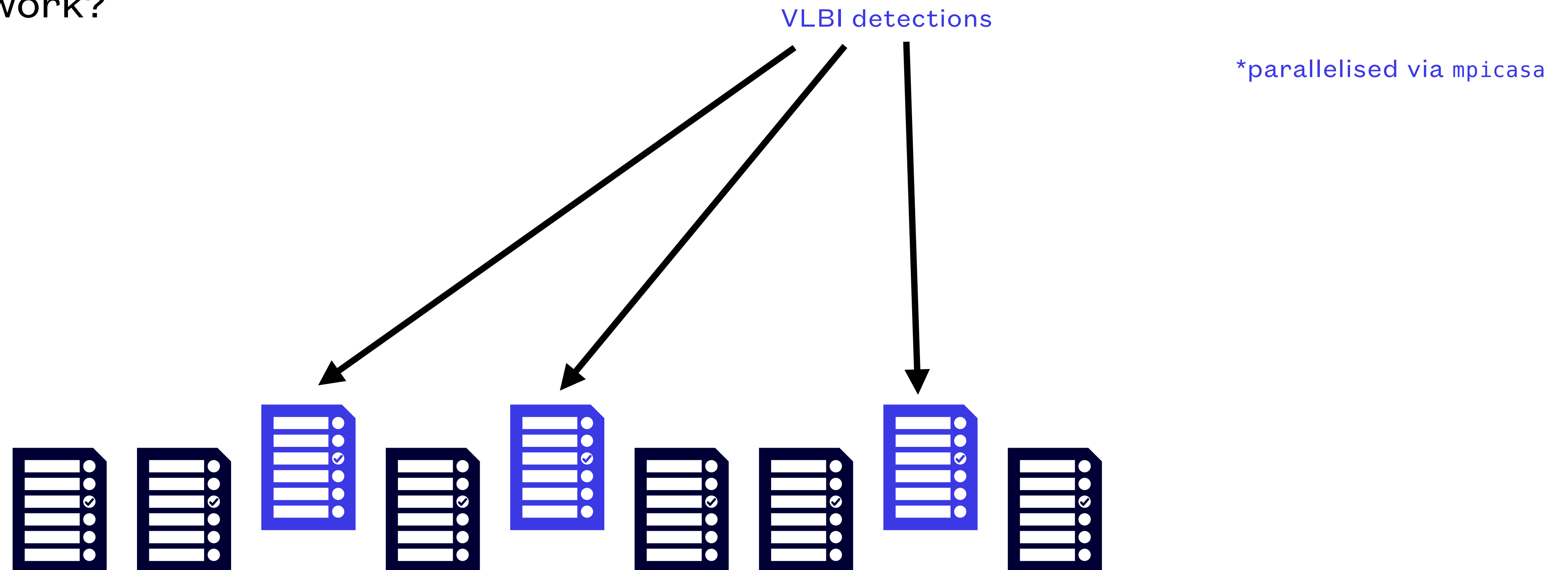




# Self-calibration solution 2

## Multi-source self-calibration (MSSC)

- Use combined response (via  $uv$  stacking) of detected target sources to derive self-calibration solutions.
- So how does it work?





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\*parallelised via mpicasa



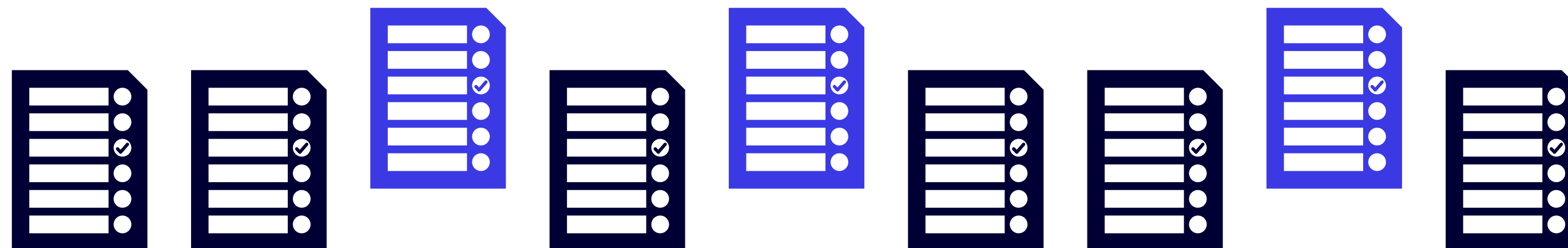
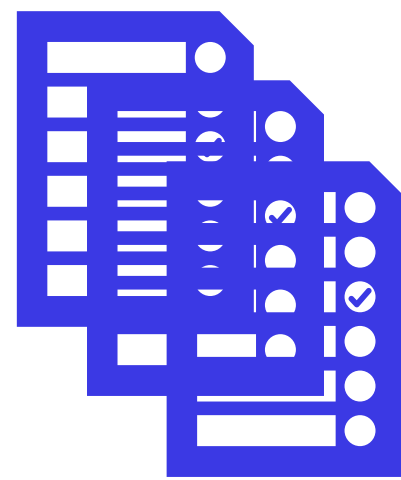


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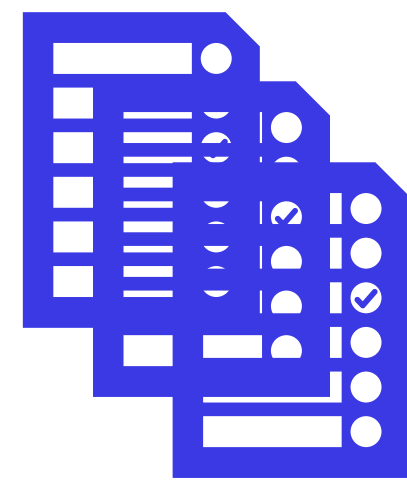


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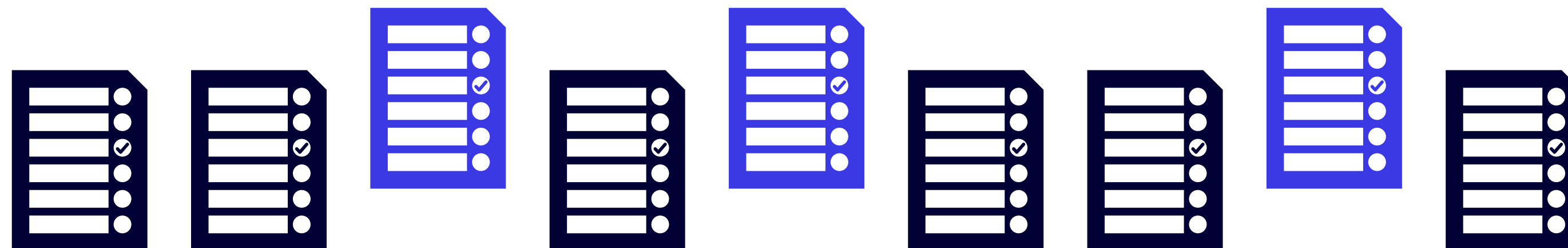
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Copy, model,  
combine &  
stack



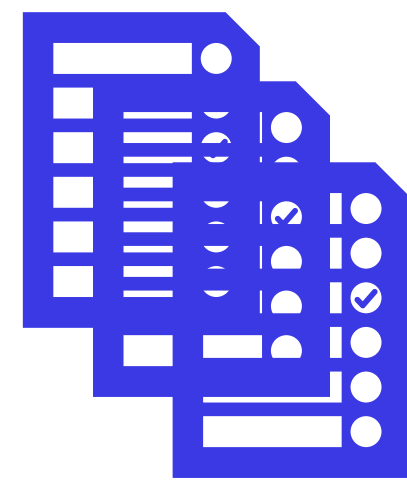


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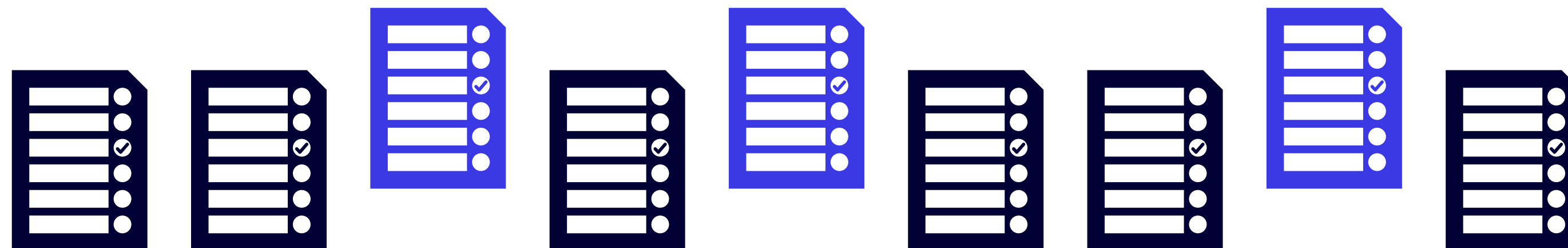
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Derive self-calibration solutions

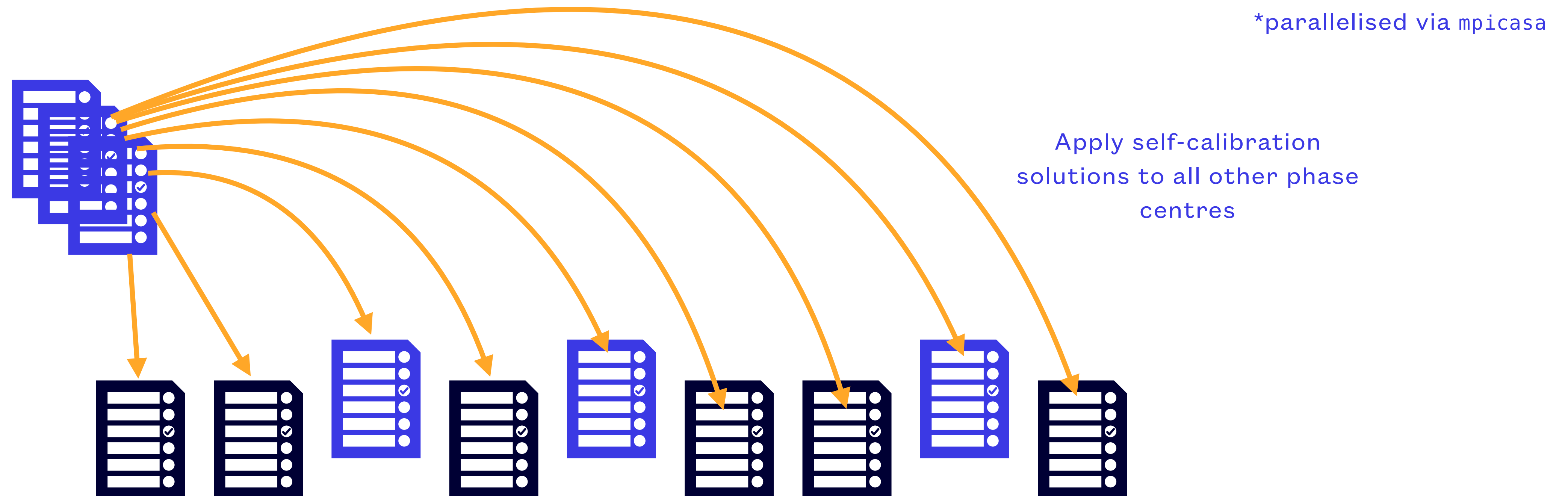




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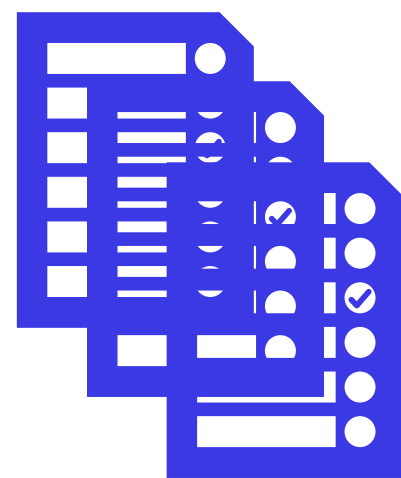
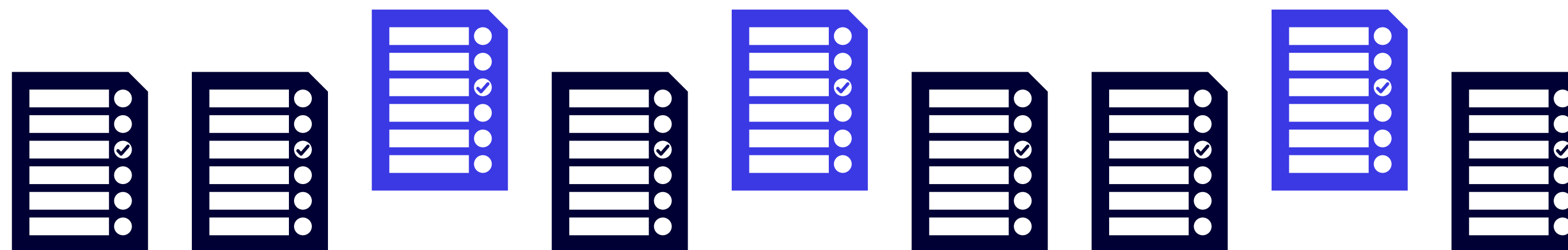


Image phase centres again (& repeat process if neccessary)

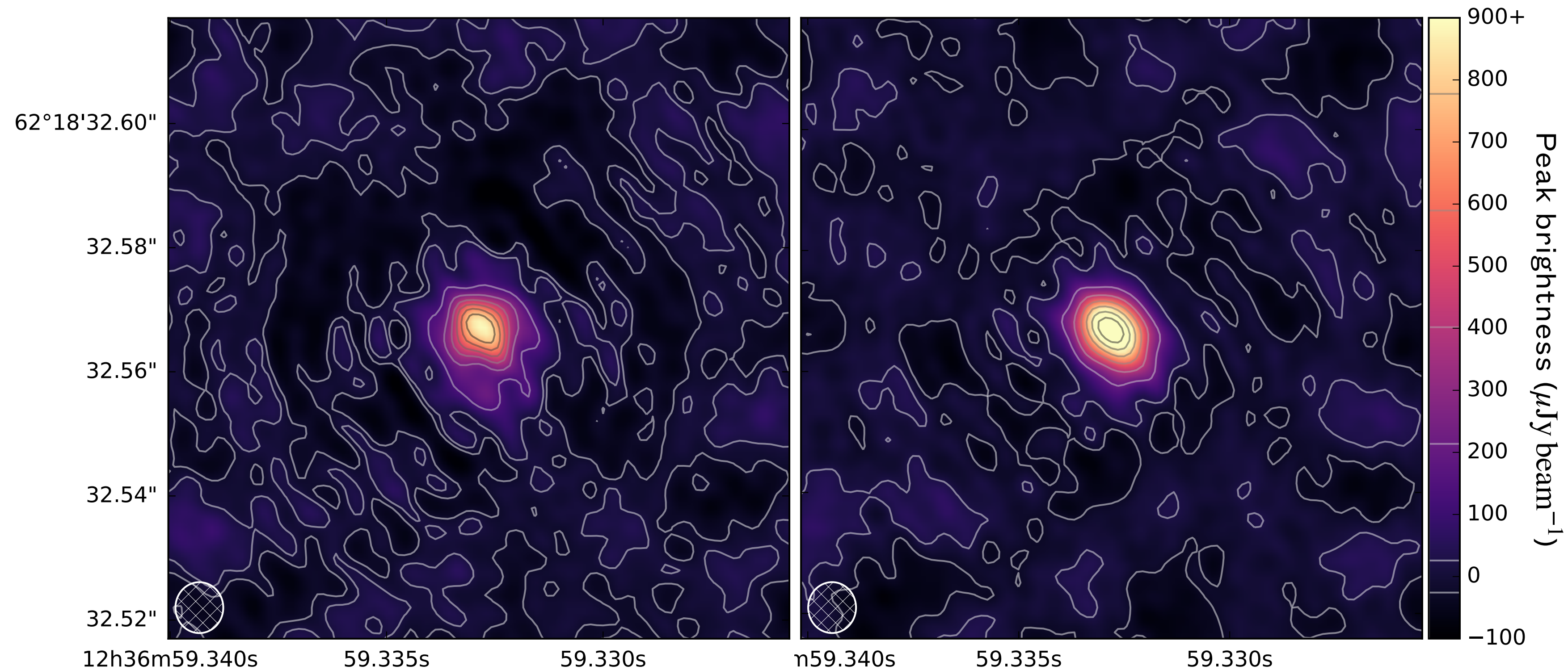




# Multi-source self-calibration

*Standard phase referencing*  
S/N ~ 43

*MSSC*  
S/N ~ 113

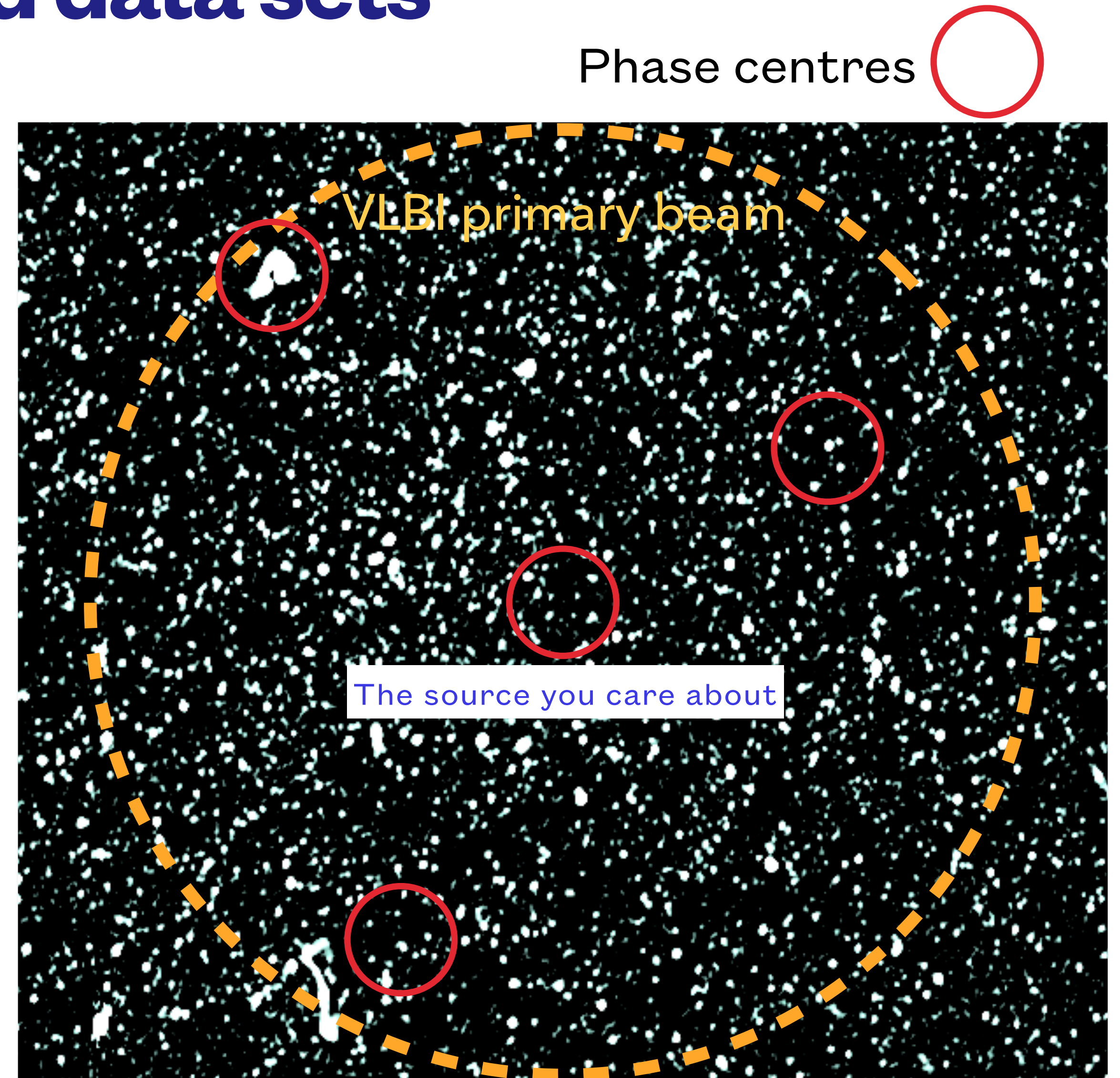


- Code publicly available for AIPS - [https://github.com/jradcliffe5/multi\\_self\\_cal](https://github.com/jradcliffe5/multi_self_cal)
- CASA version in testing stage - [https://github.com/jradcliffe5/MSSC\\_CASA](https://github.com/jradcliffe5/MSSC_CASA)



# MSSC - not just for wide-field data sets

- Standard VLBI targets just a small FoV in the centre that may not provide enough S/N for self-calibration, **but** there's other radio sources in the FoV.
- Use multiple phase centre correlation on other potential sources in the primary beam
- Then you may have enough S/N to self-calibrate VLBI data-set
- Plus you may find something interesting...

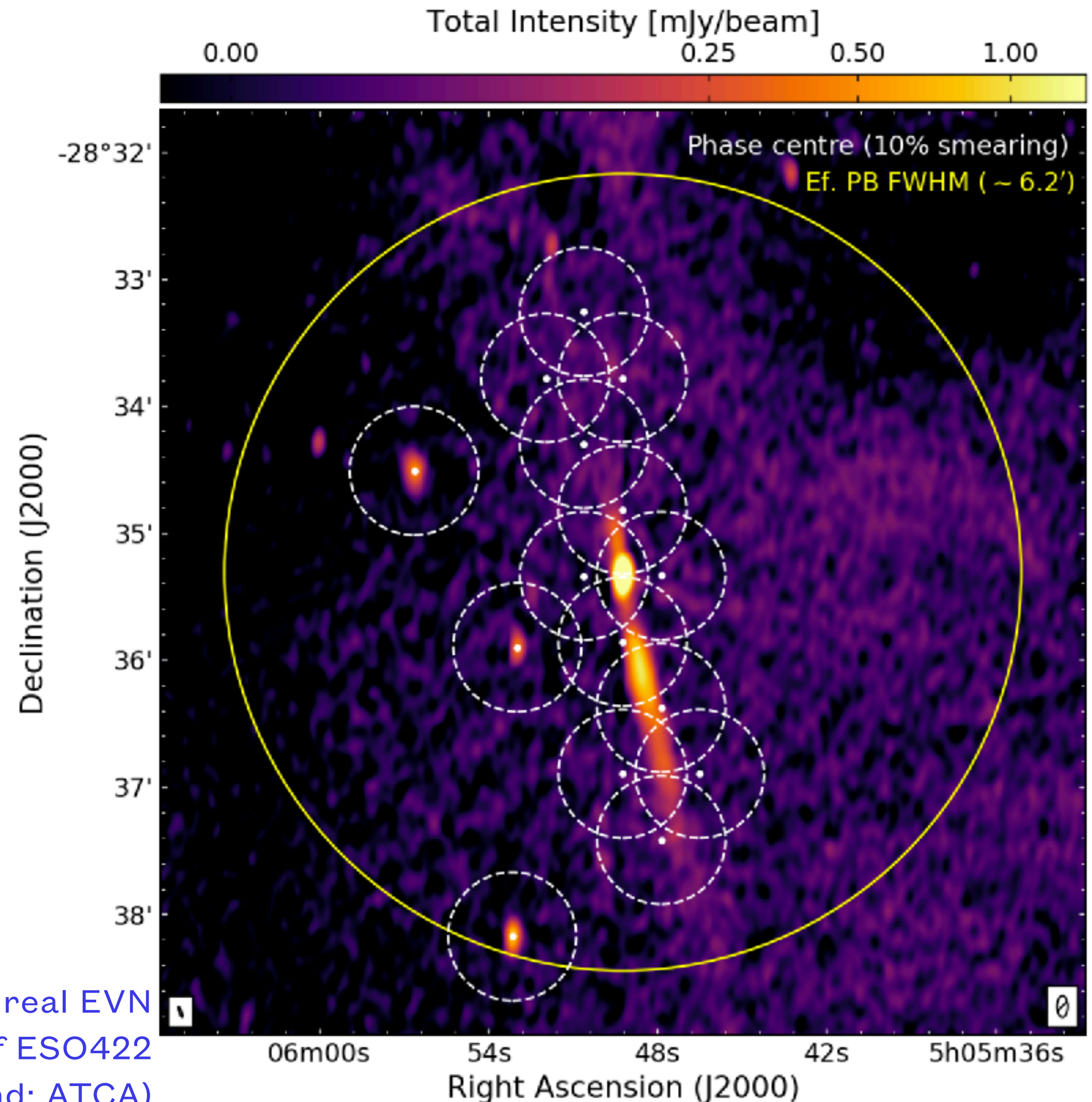




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- Plus you may find something interesting...

Example from real EVN  
observation of ESO422  
(background: ATCA)





# The primary beam problem - the final frontier for wide-field imaging

- Primary beams are *the most ubiquitous direction dependent effect* (DDE) that affects all wide-field radio observations.
- Recap of the **Radio Interferometry Measurement Equation** (RIME; Smirnov+11) for antennas  $p$  and  $q$ ,

**Visibilities** as measured by baseline  $pq$

**Sky brightness distribution**

**Directional cosines** (i.e. sky coordinates)

**Direction-independent effects (DIEs)** e.g. bandpass, complex gain errors

**Direction-dependent effects (DDEs)** e.g. primary beam, ionospheric dispersions

**Phase term -**

$$V_{pq} = G_p \left( \iint_{lm} E_p B K_{pq} E_q^H \frac{dl dm}{n} \right) G_q^H$$

$n = \sqrt{1 - l^2 - m^2}$

$K_{pq} = \exp \left\{ -2\pi i \left[ u_{pq} l + v_{pq} m + w_{pq} (n - 1) \right] \right\}$

- More of a problem for heterogeneous arrays (i.e. most VLBI arrays) as we shall see next.



## The primary beam problem - homogeneous arrays

- Assume DfEs ( $\mathbf{G}$ ) are calibrated and no other DDEs are present so  $\mathbf{E}$  are just the primary beam voltages.
- For an homogeneous array e.g. MeerKAT, VLA, ASKAP etc. standard assumption is that the primary beam for each telescope is identical ( $\mathbf{E}_p = \mathbf{E}_q = \mathbf{E}$  for all  $p, q$ ) and non-varying with time so  $\mathbf{E}(t, l, m) \equiv \mathbf{E}(l, m)$ .
- This means that *each baseline observes the same apparent brightness distribution* thus,

$$\mathbf{B}_{\text{app}} = \mathbf{E}\mathbf{E}^H$$

- Standard imaging algorithms recover an image by *assuming that each baseline observes the same apparent brightness distribution / common sky*. Due to this, all of the baselines can be gridded so their projected baseline vectors form the  $uv$  plane,

$$V(u, v) \approx \iint_{lm} \mathbf{B}_{\text{app}} \exp \left\{ -2\pi i \left[ ul + vm + w(n - 1) \right] \right\} dl dm$$



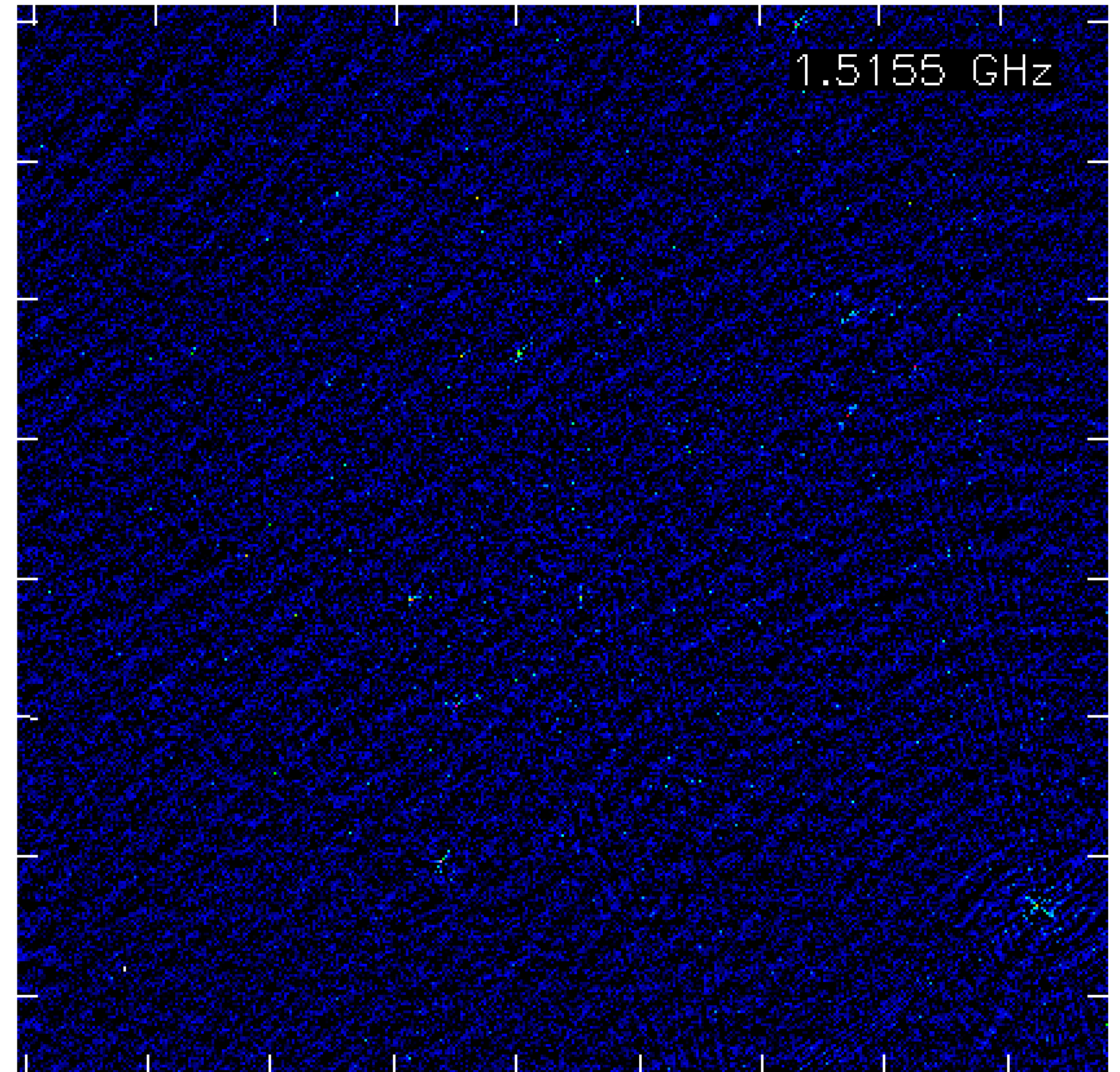
# Homogeneous arrays

- This is our standard imaging problem and can be gridded, inverted, and de-convolved to recover  $B_{\text{app}}$ .
- We can then recover the true sky brightness distribution via,

$$B(l, m) = \frac{B_{\text{app}}}{|E(l, m)|^2}$$

- Images generated will simply be the true brightness attenuated by some power beam
- Thus the true source flux density can be recovered by dividing the image with the power beam response.

The GOODS-N field as seen by the VLA





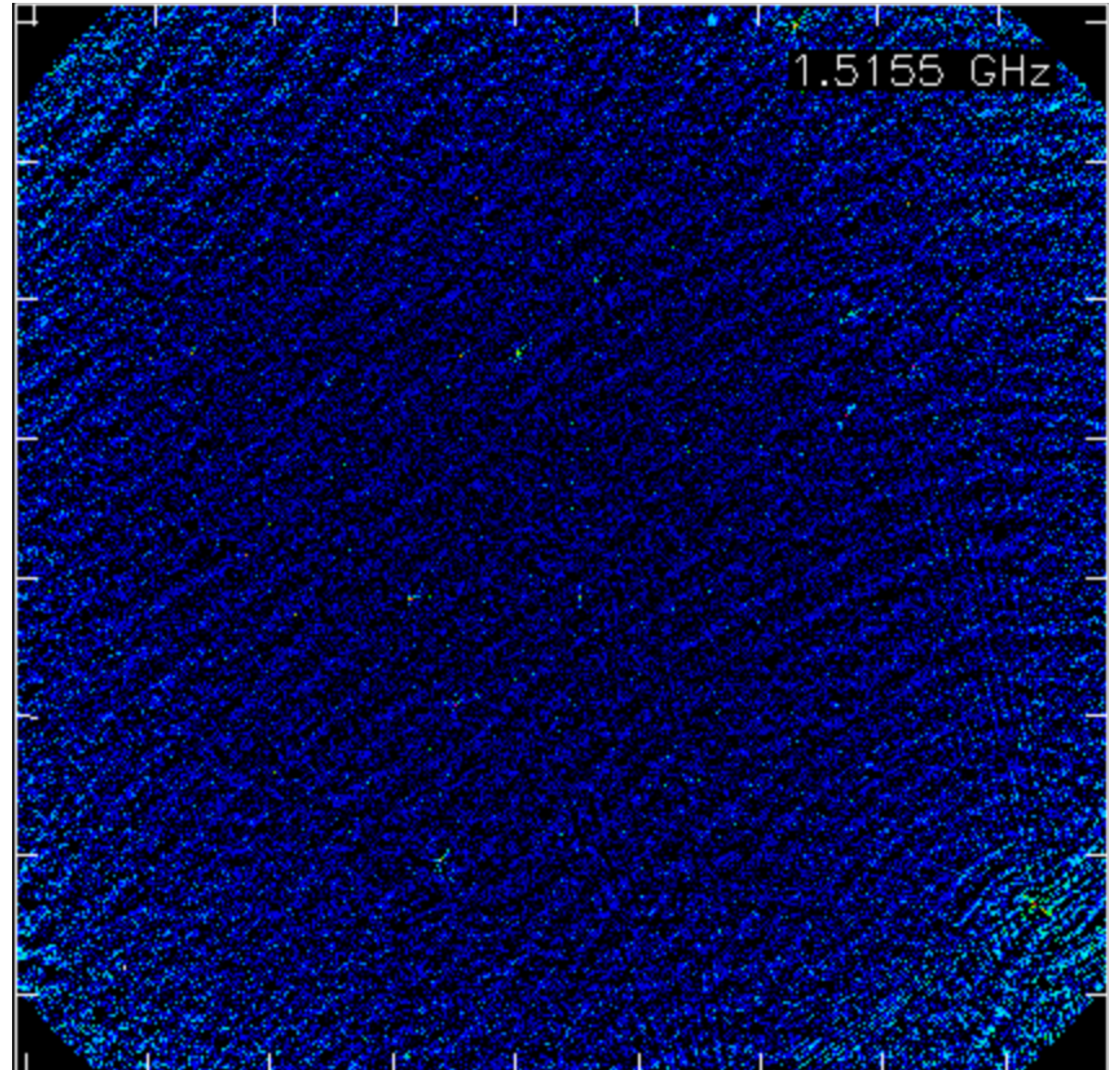
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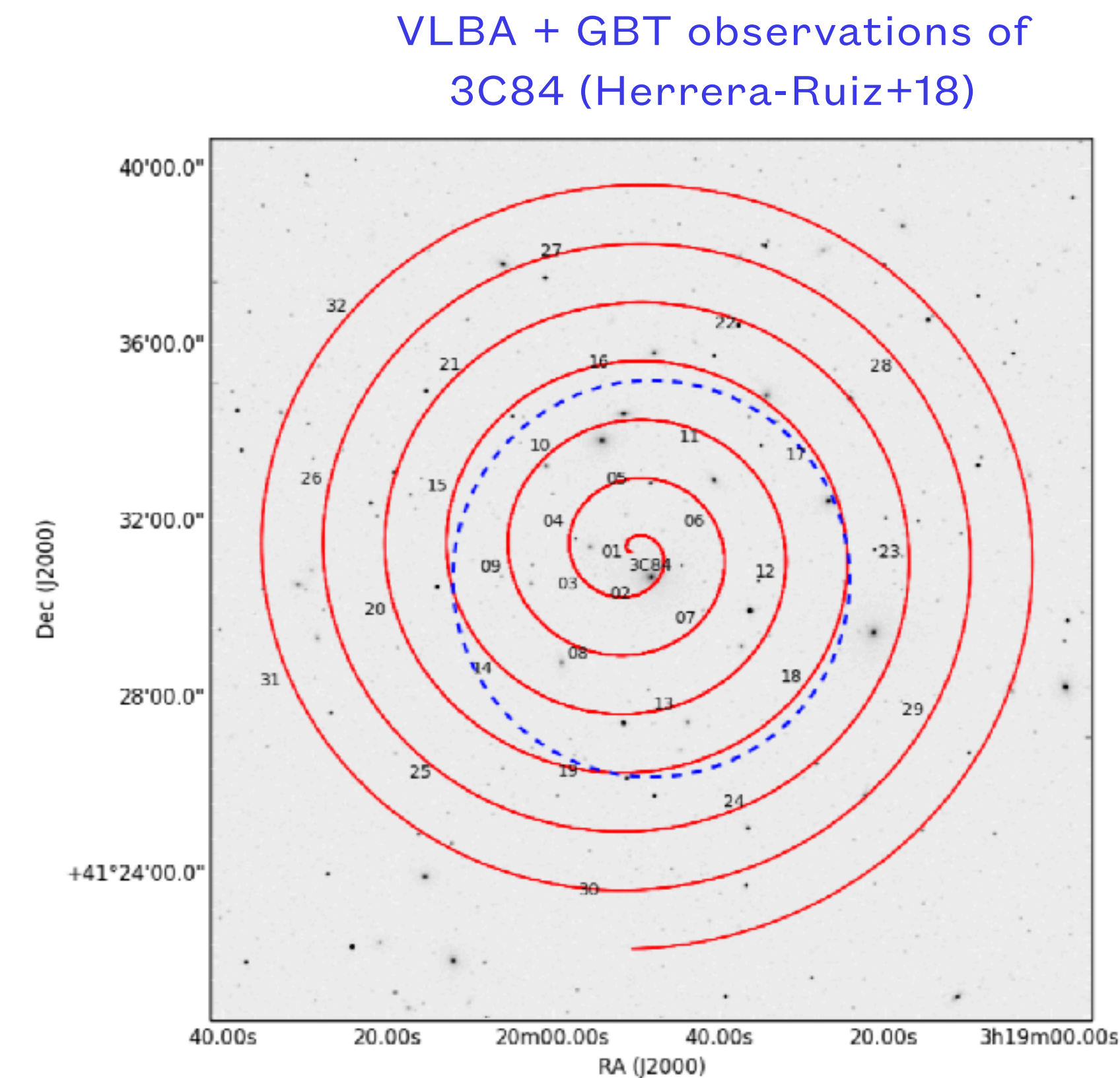
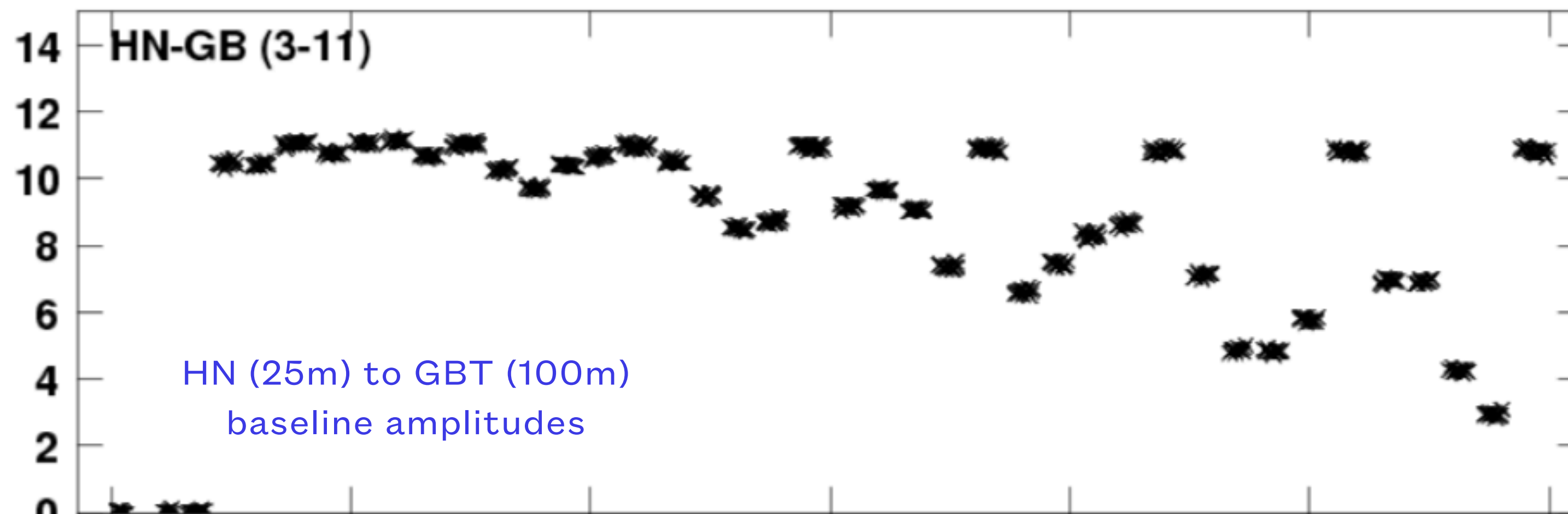


# Heterogeneous arrays

- Not so simple for a heterogeneous array. Big issue comes from the following,

$$B_{\text{app},pq} = E_p B E_q^H \neq B_{\text{app},pq} \text{ for all } p, q$$

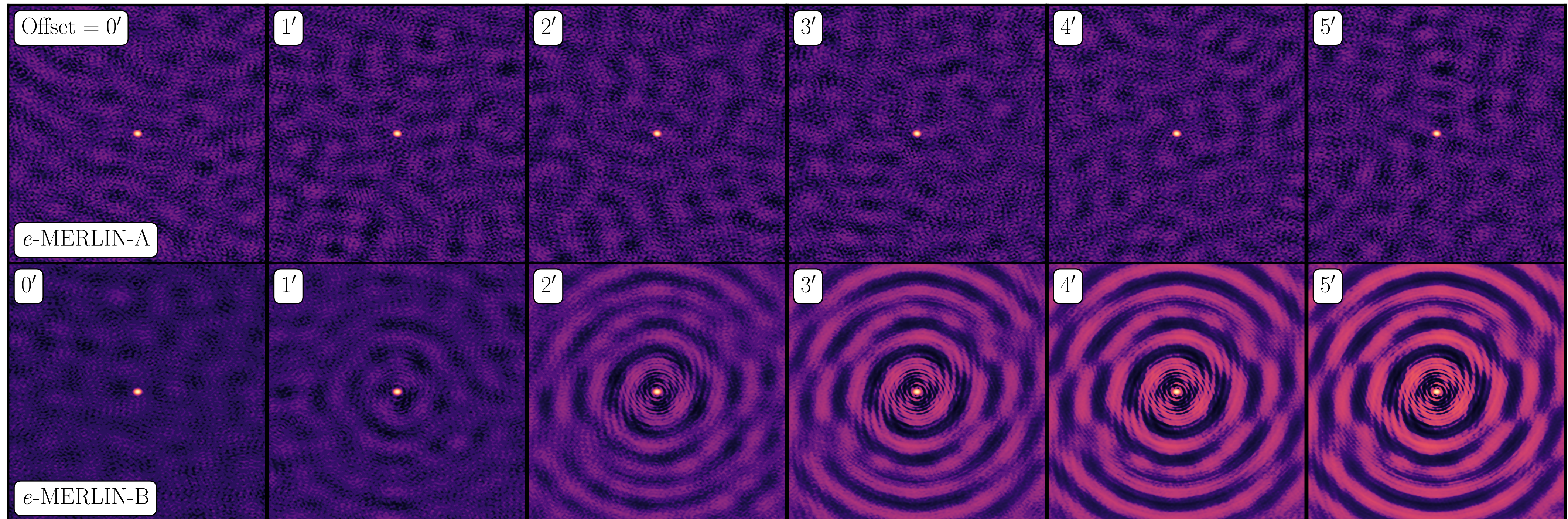
- i.e. **each baseline does *not* observe the same apparent brightness distribution**
- This manifests as a *direction-dependent, antenna independent, and dominant, amplitude (and phase...) error*. e.g.





# Heterogeneous arrays

- This is more of a problem for very heterogeneous arrays (e.g. the EVN) and can drastically limit dynamic range quite close to the pointing centre.
- Below is a simple simulation of e-MERLIN-A (approx. homogeneous) and e-MERLIN-B (heterogeneous with two telescope sizes) arrays observing on a point source with dynamic range of 1000 at different offsets from pointing centre.



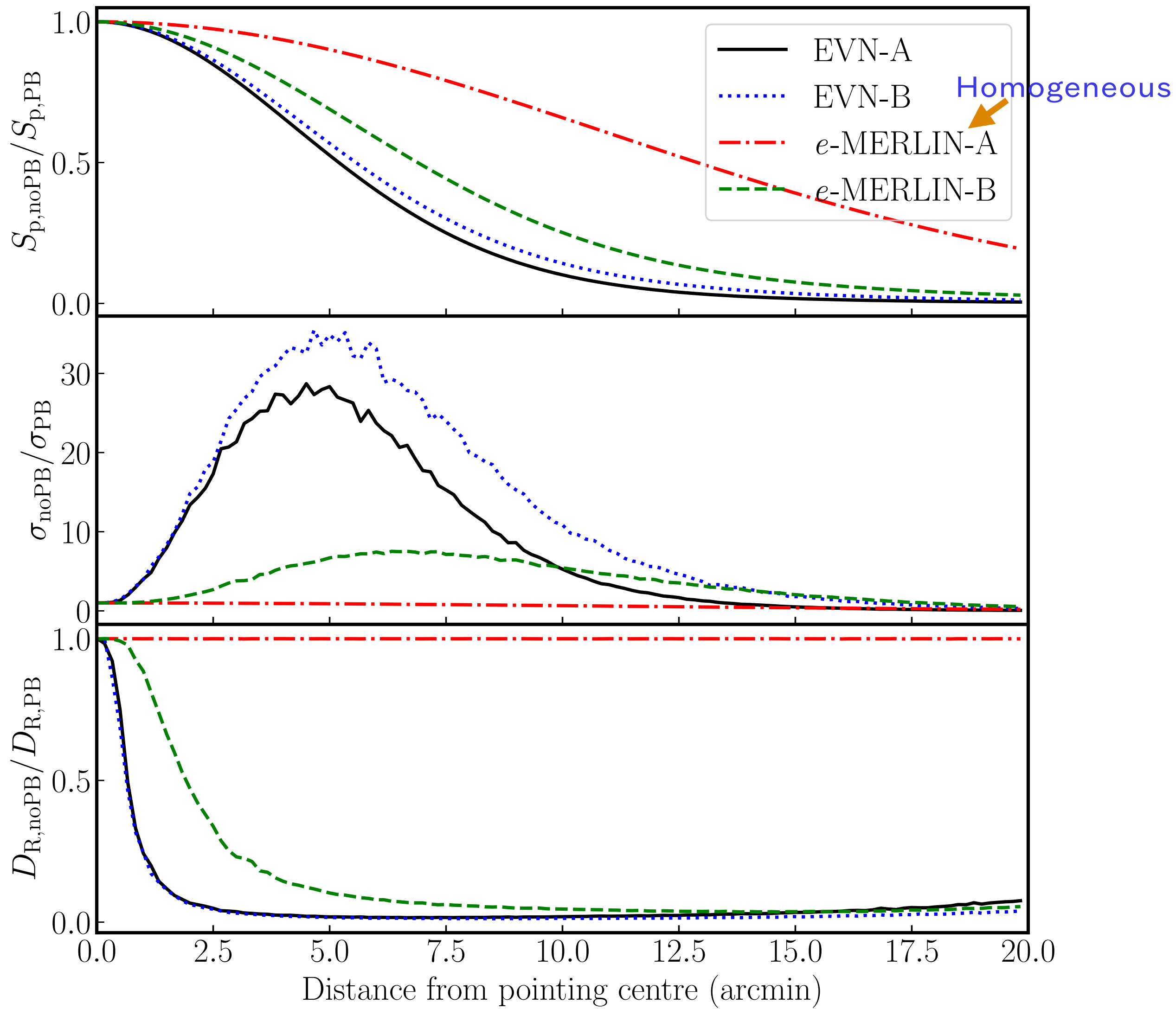


# Heterogeneous arrays

- This can be even more severe for EVN arrays:

Simulation name	Stations	$N_{\text{ant}}$	$N_{\text{pb,unique}}$
<i>e</i> -MERLIN-A	Jb-2, De, Kn, Pi, Da	5	1
<i>e</i> -MERLIN-B	Jb-1, Dc, Kn, Pi, Da	5	2
EVN-A	Jb-1, Ef, Tm-65, Wb, On-85, Tr, Sv, Bd, Zc, Ur	10	4
EVN-B	Jb-1, Ef, Tm-65, Wb, On-85, Tr, Sv, Bd, Zc, Ur, De, Kn, Pi, Da, Cm	15	5

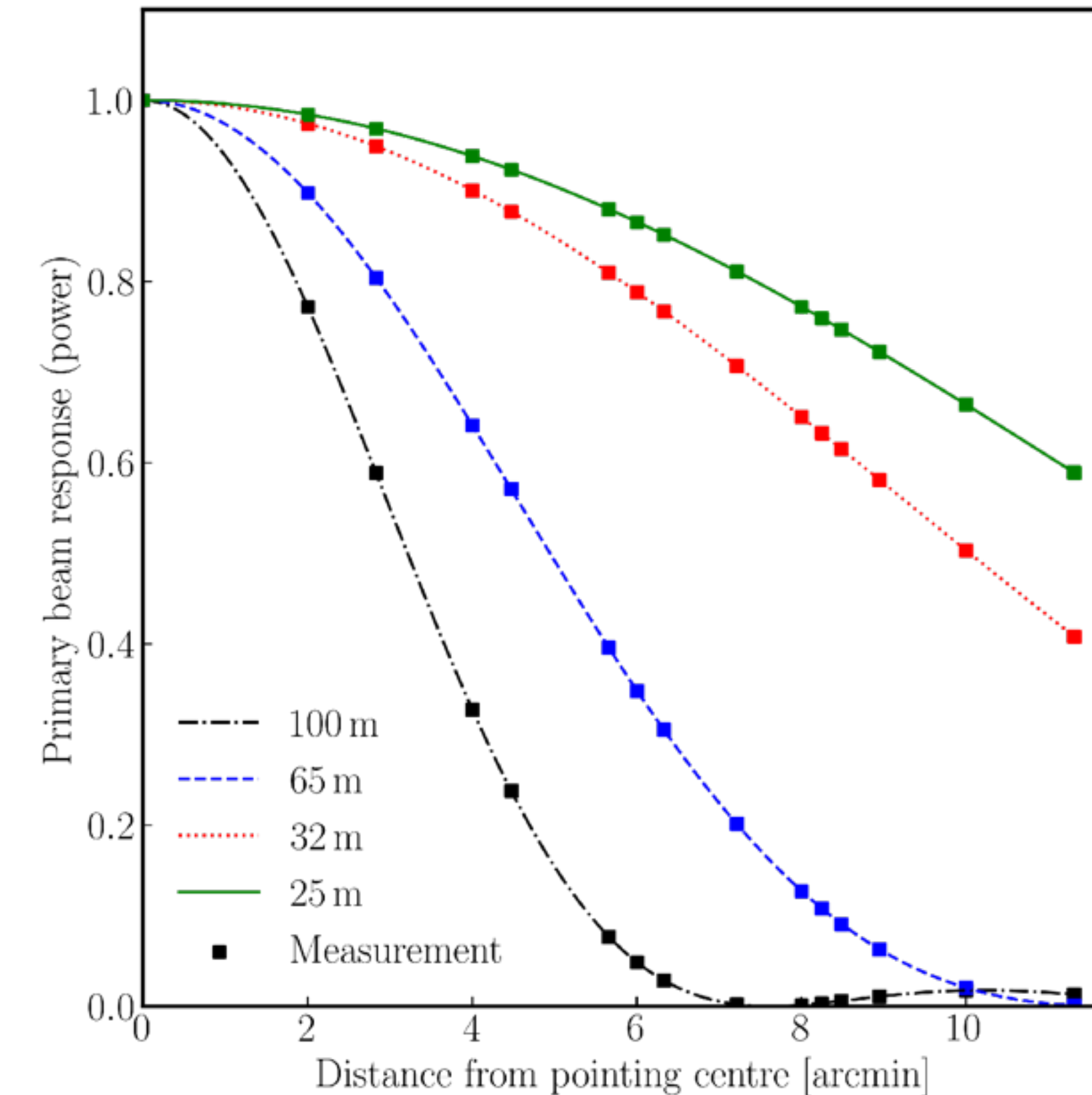
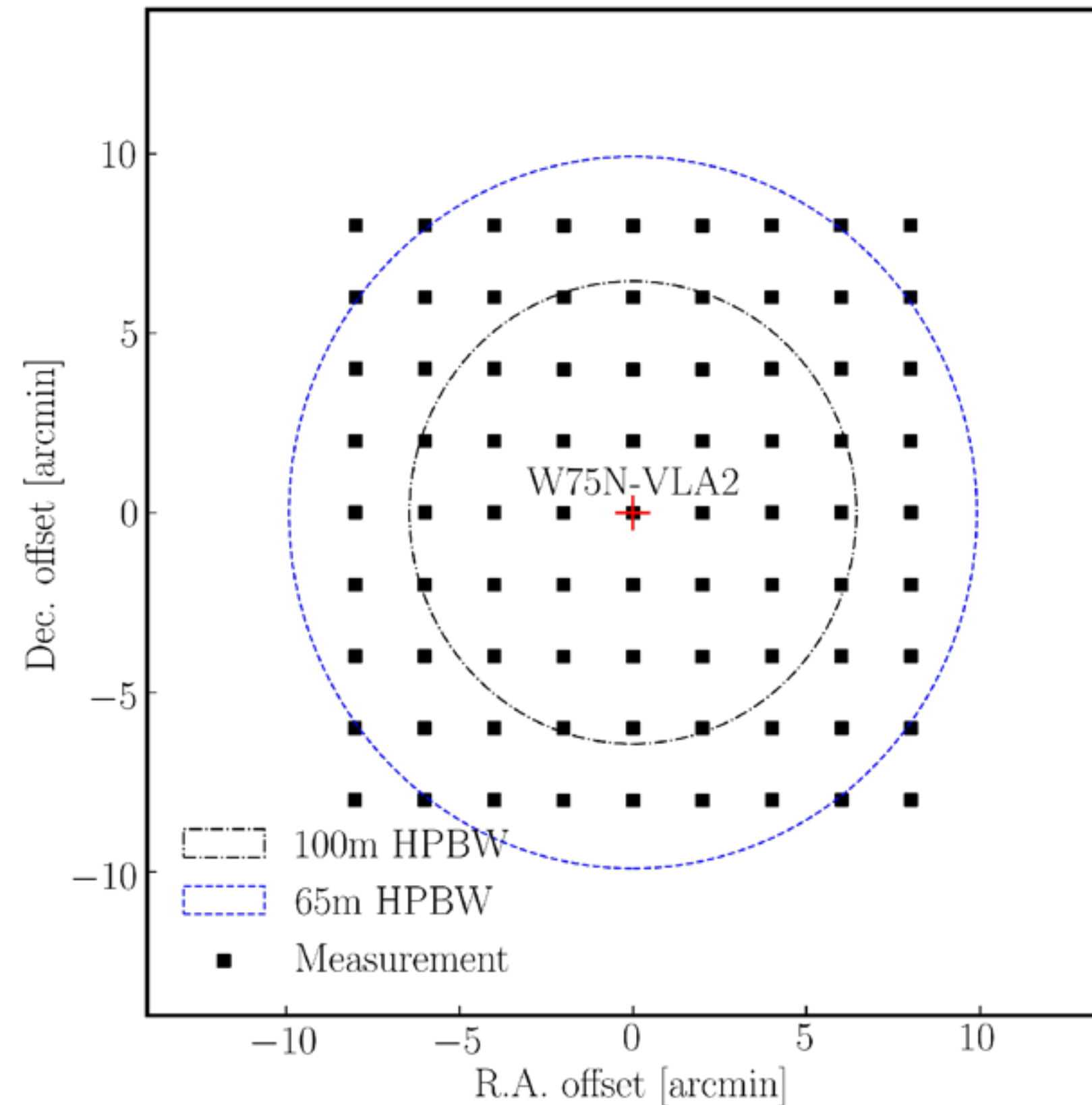
- This error is proportional to source dynamic range so primary beam errors not too severe at low S/N.
- Will become ever more important with increasing VLBI bandwidths and inclusion of sensitive (phased-up) elements e.g. MeerKAT / SKA.
- To correct this effect, we need models of the primary beams!





# Primary beam models - current status

- VLBA and GBT estimates exist (e.g. Middelberg+2013)
- Some for e-MERLIN (Wrigley 2016) but about to be updated for whole array.
- Only a few at 1-2 GHz for the EVN but all is about to change! Accepted proposal (EVN + e-MERLIN joint effort) to map EVN stations.
- Current primary beam models at 1-2 GHz are crude estimates (taking into account blockages etc.; see Radcliffe+18)



Mapping the primary beam of EVN and e-MERLIN stations at 1.6 GHz by observing bright maser source W75N-VLA2. Results expected in Q2 2021.



# Primary beam correction schemes

- With beam models / approximations at hand, how do we apply these corrections for heterogeneous arrays (and wide-field VLBI data)?
- Currently three ways,
  - a. Image plane correction (primarily homogeneous arrays only)
  - b. ‘Differential’ / step-wise primary beam correction
  - c.  $uv$ -plane correction i.e.  $a$ -projection



## a. Image plane correction

- Can calculate total power beam,  $P_T$ , for heterogeneous array via,

$$P_{pq}(l, m) = \frac{E_p E_q^* + E_q E_p^*}{2\sqrt{W_p(\nu)W_q(\nu)}}$$

Baseline primary beam  $\rightarrow$

Voltage beam for antenna p/q

Weights of antenna p / q

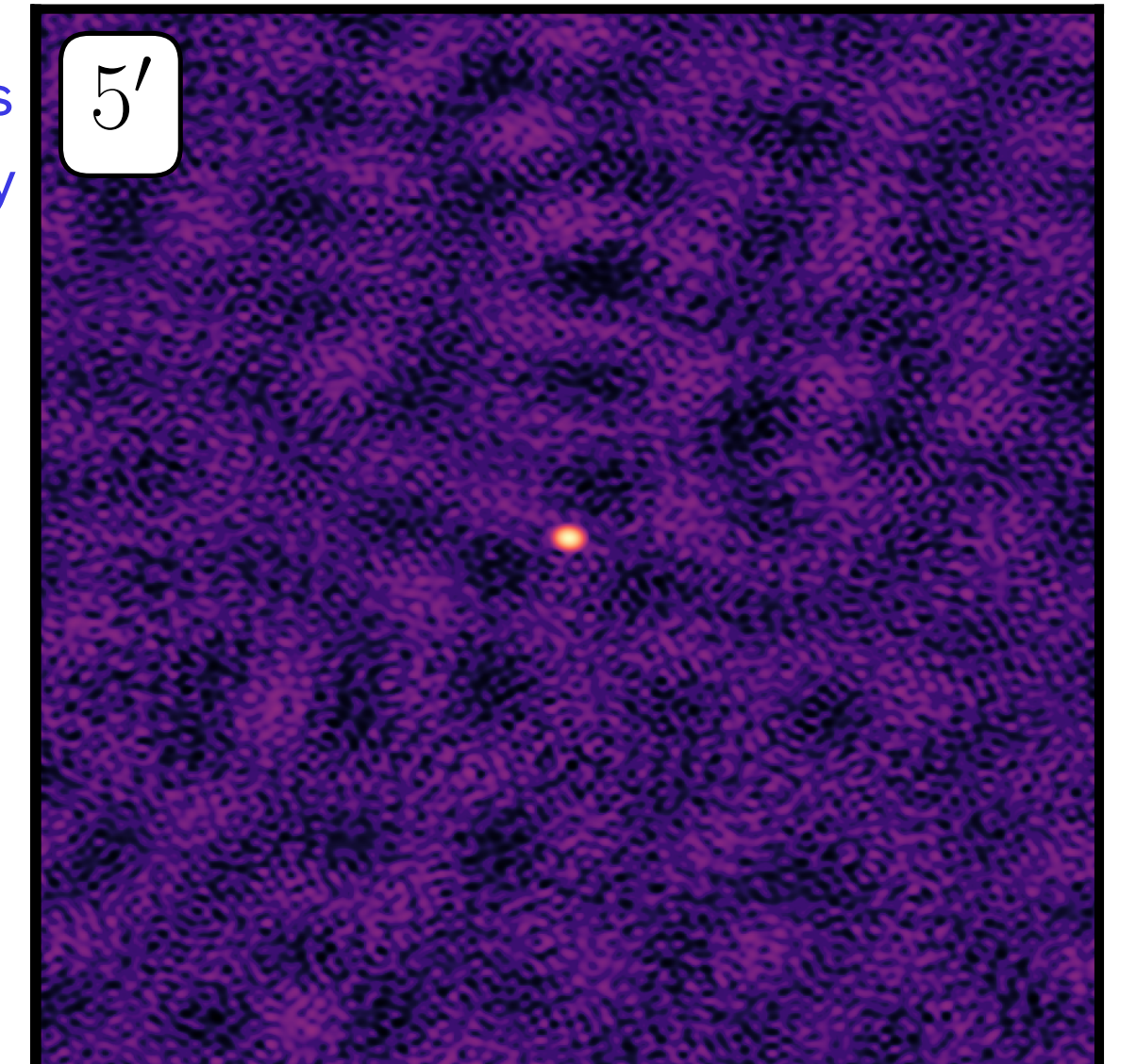
$$P_T = \sum_{i,j=0;j>i}^{N_{\text{ant}}} P_{pq}$$

(Weighted) sum over all baselines

- and divide subsequent image by  $P_T$ .
- Provides a scalar shift in the image plane (partially fixing flux densities) but **does not** correct for the direction-dependent antenna independent errors.
- You can fix amplitude errors for some sources via self-calibration but crucially not all.

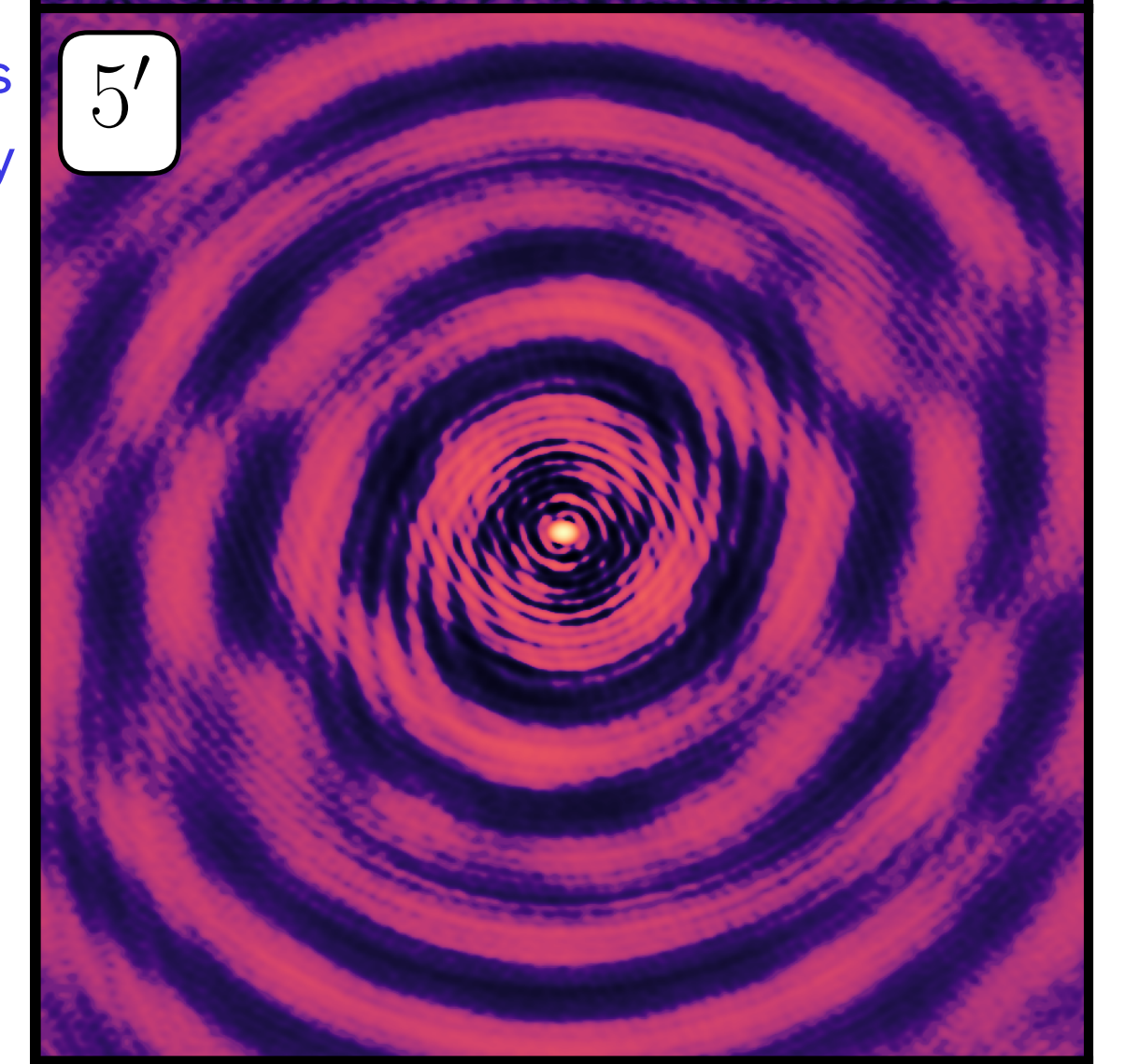
Homogeneous  
array

5'



Heterogeneous  
array

5'





## b. ‘Differential’ / step-wise primary beam correction

- Correct each phase centre in  $uv$  plane using gain table with a singular value for each antenna’s primary beam voltage, evaluated at centre of the phase centre (where  $l = l_{pc}$  and  $m = m_{pc}$ ). Effectively does the following to each baseline,

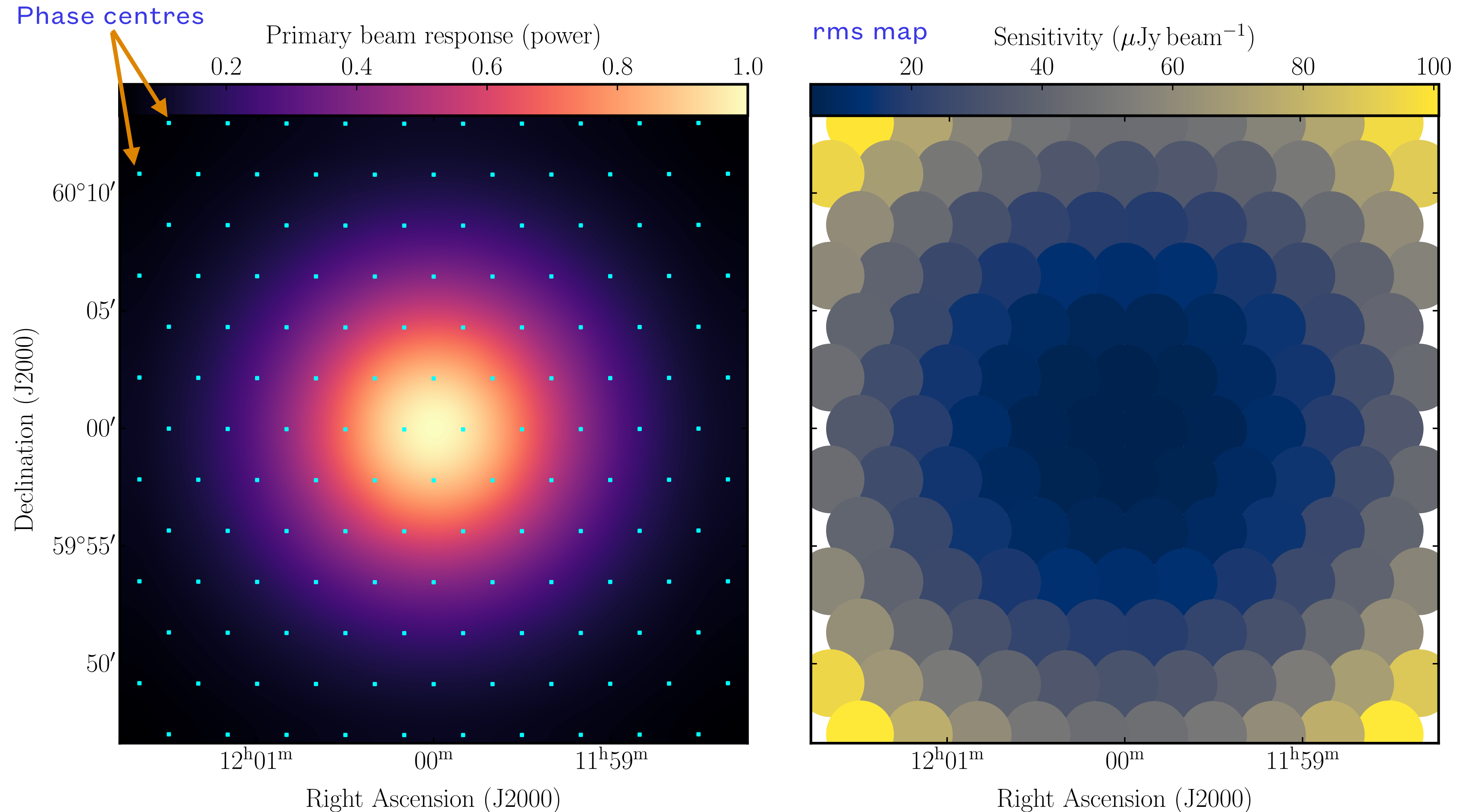
$$V_{pq,obs}(l_{pc}, m_{pc}) = \frac{V_{pq,obs}}{\mathbf{E}_p(l_{pc}, m_{pc}) \mathbf{E}_q^H(l_{pc}, m_{pc})}$$

- (Sometimes conducted) → outside of the phase centre centre, calculate error difference between real primary beam response and  $uv$  corrected response, and correct in the image plane to recover true fluxes.
- Note that this *only perfectly corrects amplitude errors at centre* of each phase centre.
- Residual amplitude errors proportional to  $\nabla \left| \mathbf{E}_p \mathbf{E}_q^H \right|$ , distance from centre of phase centre & primary beam model errors **but errors are much smaller** than image plane only correction!



## b. ‘Differential’ / step-wise primary beam correction

- 12 hour simulated EVN observation (central rms  $\sim 4 \mu\text{Jy beam}^{-1}$ )

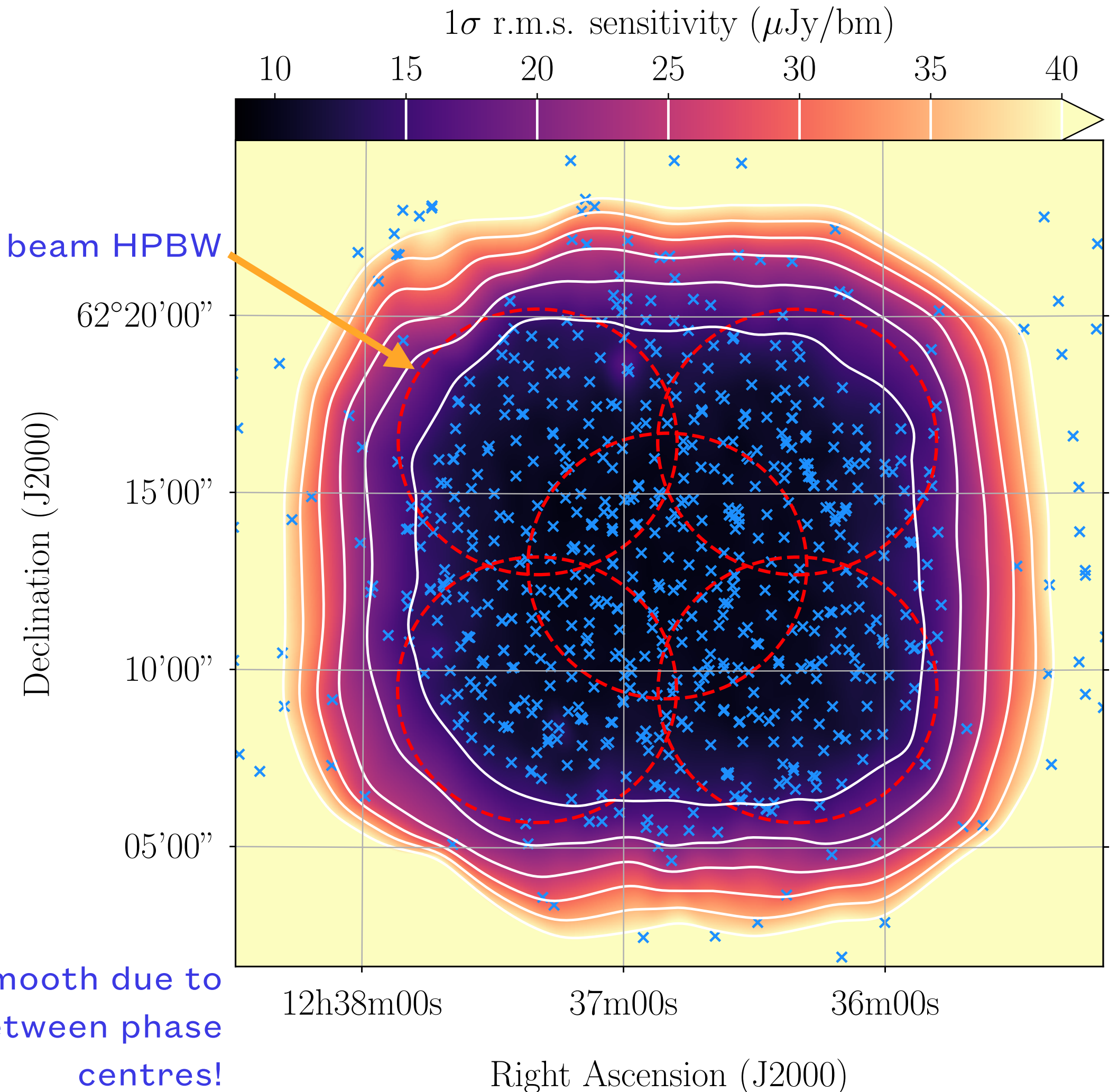




## b. ‘Differential’ / step-wise primary beam correction

- This is the current method used in published wide-field VLBI studies.
- *AIPS*
  - For VLBA - AIPS task CLVLB (Middelberg+13, Herrera-Ruiz+18)
  - For EVN (using Parseltongue) - [https://github.com/jradcliffe5/EVN\\_pbcor](https://github.com/jradcliffe5/EVN_pbcor) (Radcliffe+18) or given by the EVN pipeline output.
- CASA conversions currently being tested.

EVN primary beam correction on real data (Radcliffe+18)





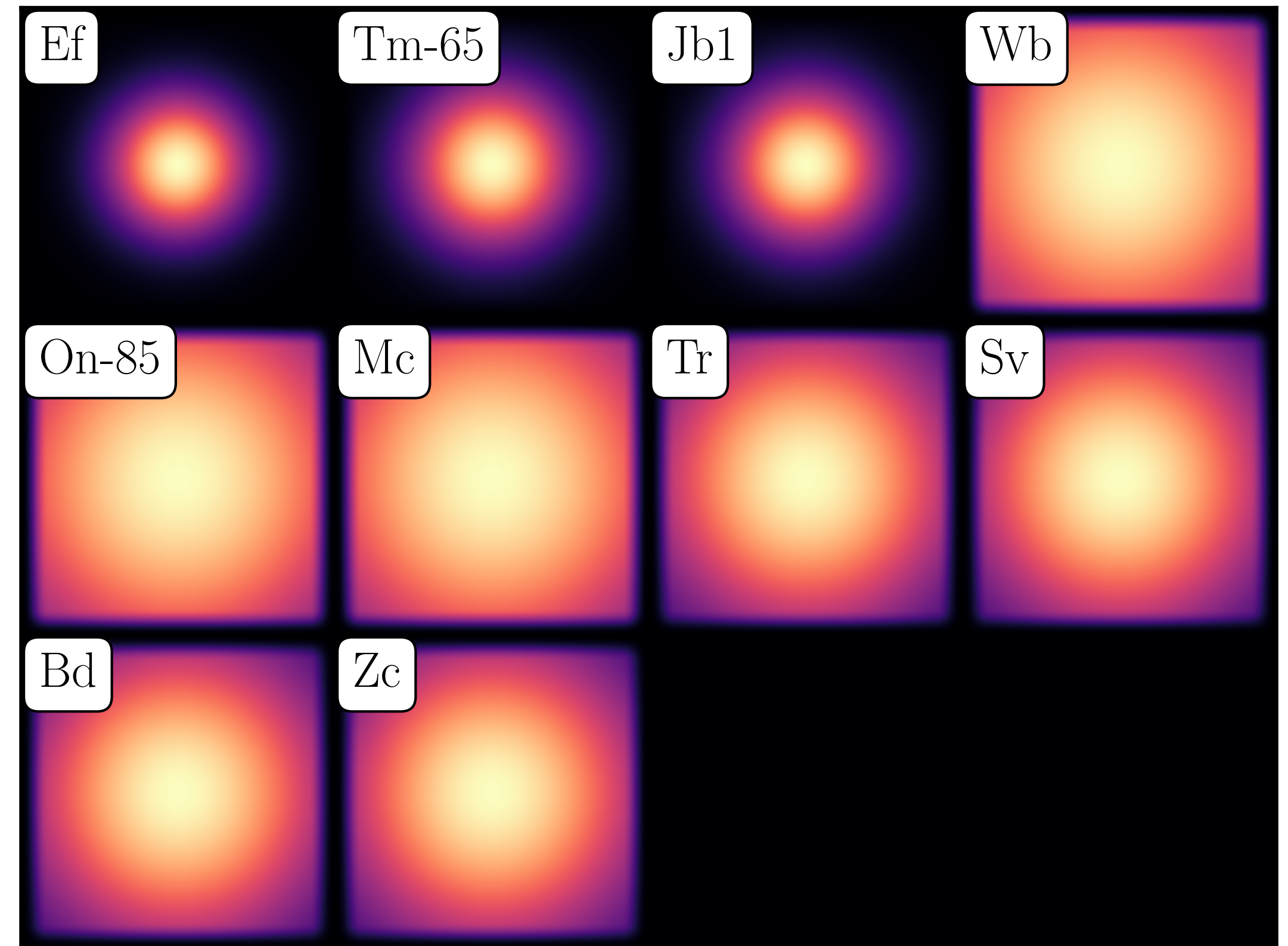
## c. $\alpha$ -projection

\*Same 12 hour simulated EVN  
observation (central rms  
 $\sim 4 \mu\text{Jy beam}^{-1}$ )

- New method corrects for primary beam response while gridding visibilities.
- Implemented in the Image Domain Gridding (IDG) as part of the wsclean imaging package.
- Will correct for primary beam effects with smaller error than other methods.
- Method can also implement:
  - More complex beams (e.g. true frequency dependence - i.e. not  $1/\lambda$ , beam rotation of sidelobes etc.)
  - And other direction-dependent effects (e.g. pointing errors, TEC dispersion etc.)

*All these correction schemes implemented / planned in cm-VLBI pipeline (not native to CASA)*

$\alpha$ -projection kernels



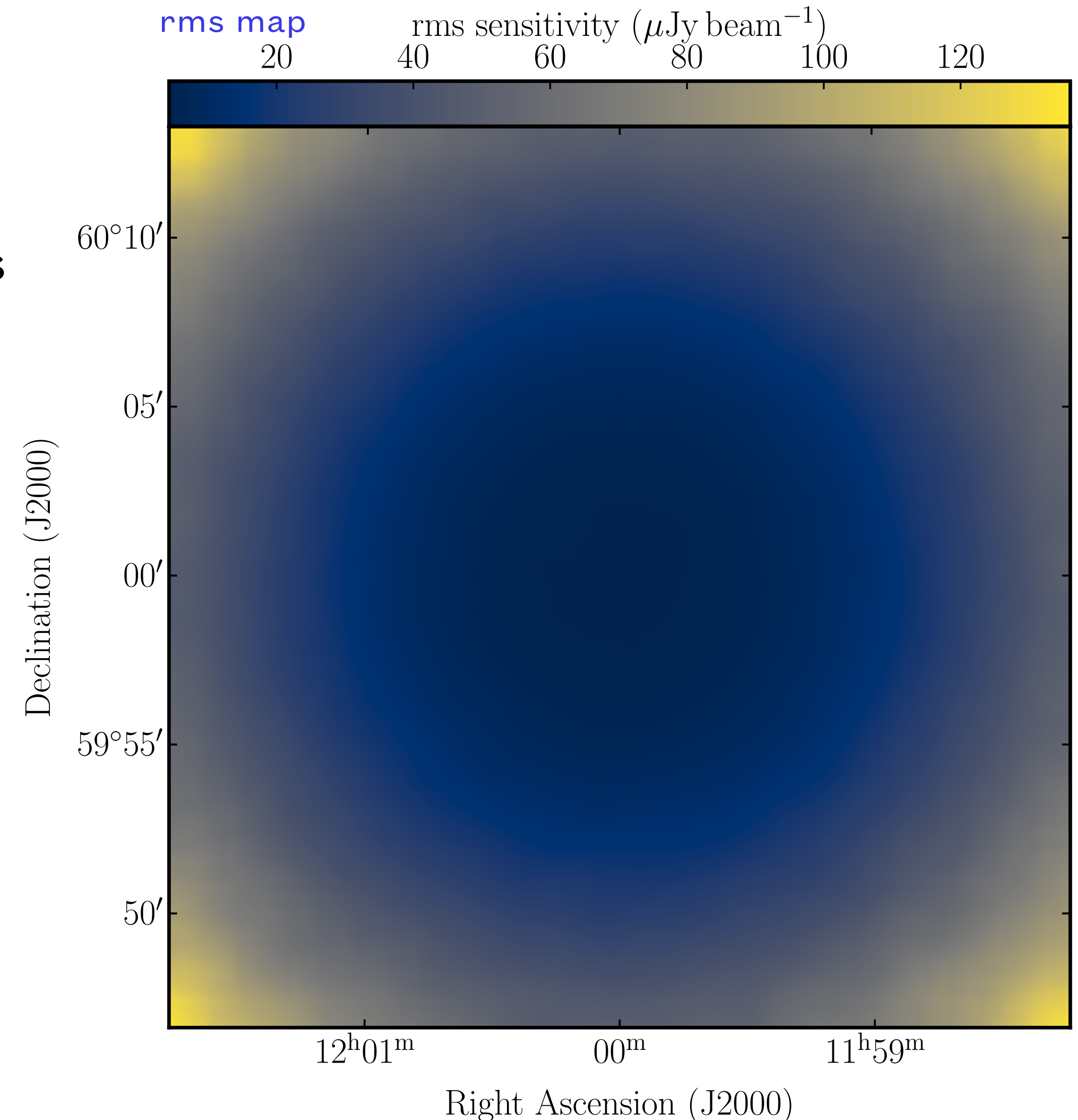


## c. $\alpha$ -projection

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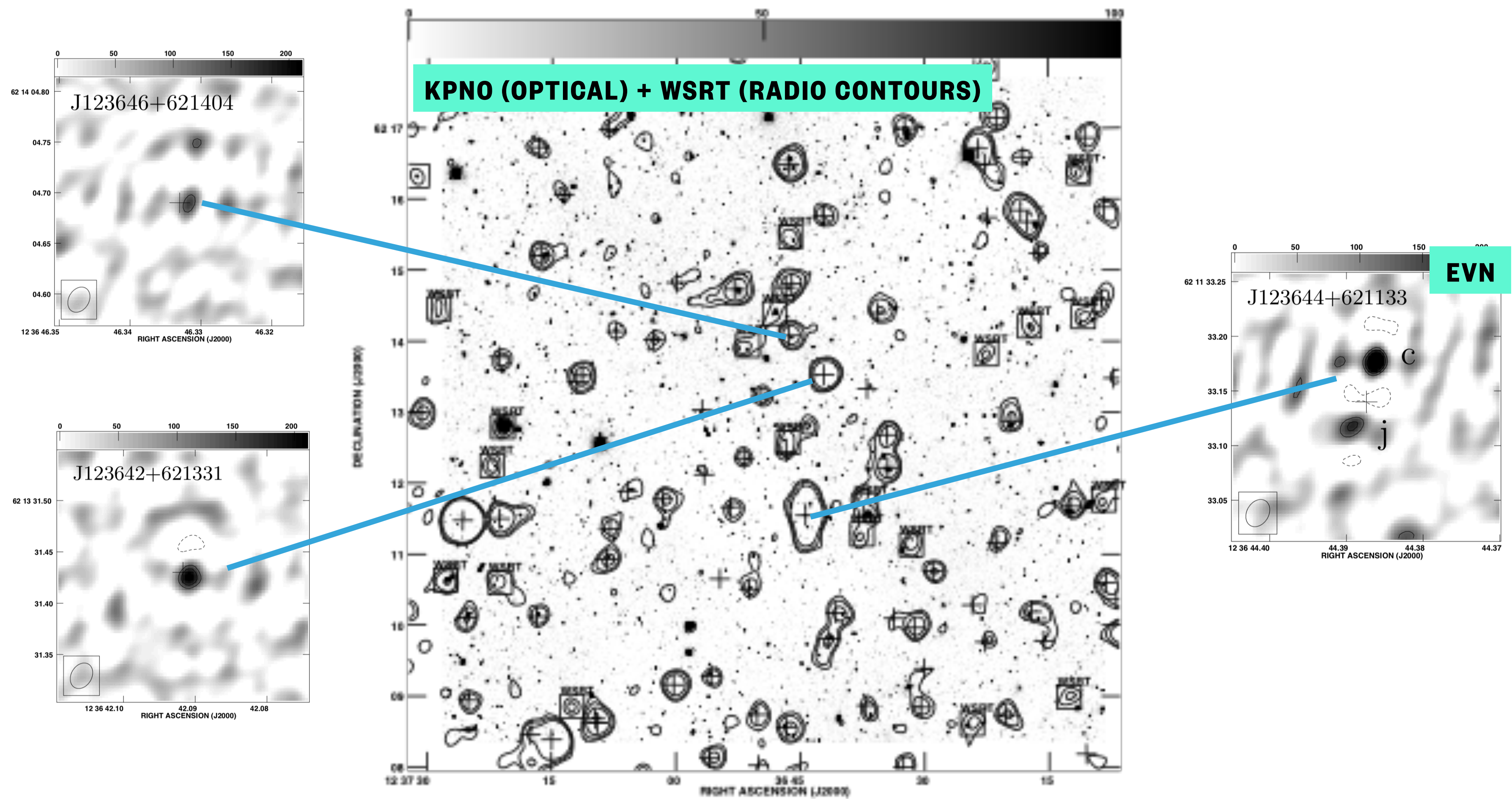




# With these advancements...

We went from this 19 years ago in the GOODS-N field

Garrett+00



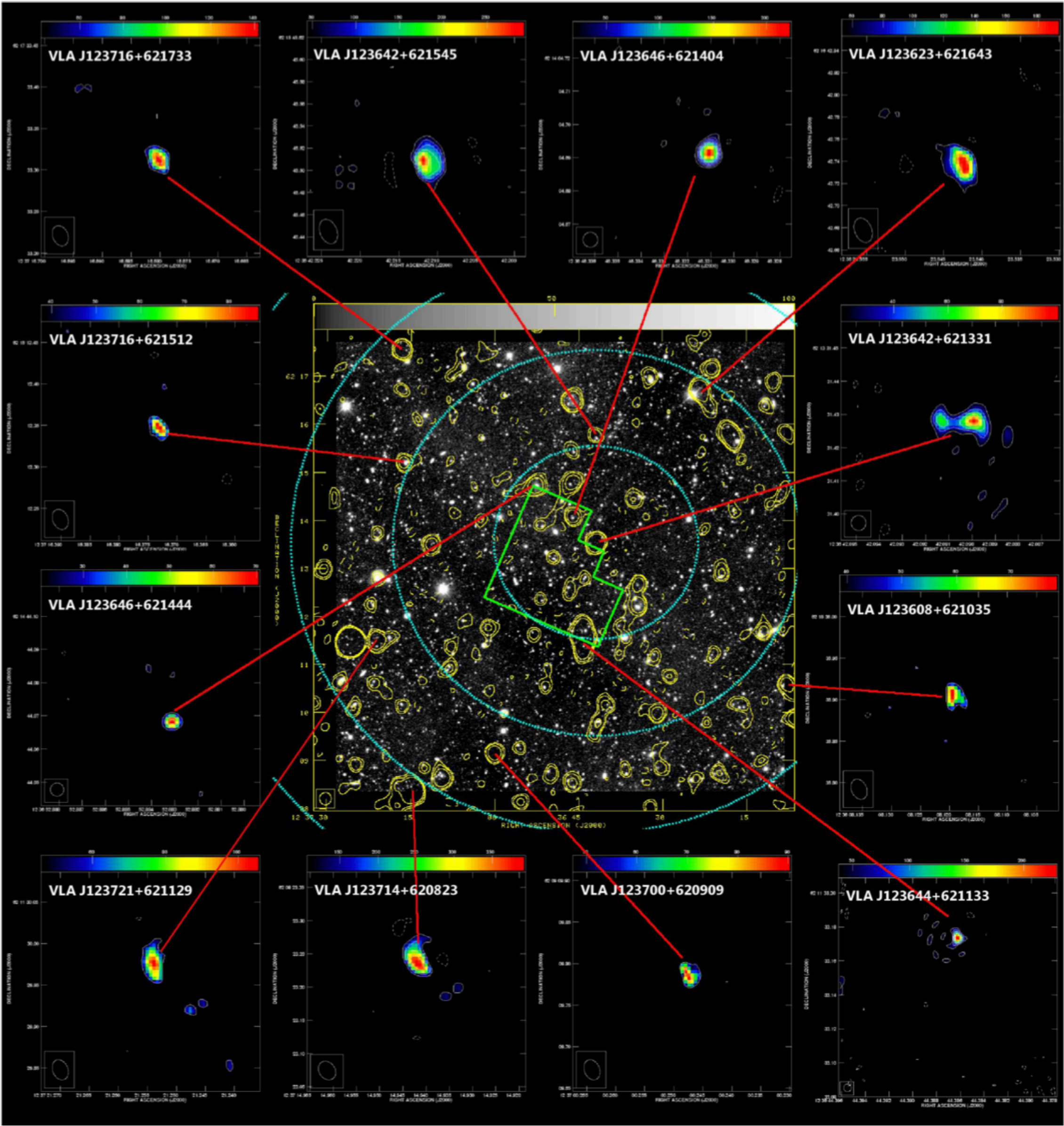


4. CONCLUSIONS

... to ...

Chi+13

Observed 15 years ago



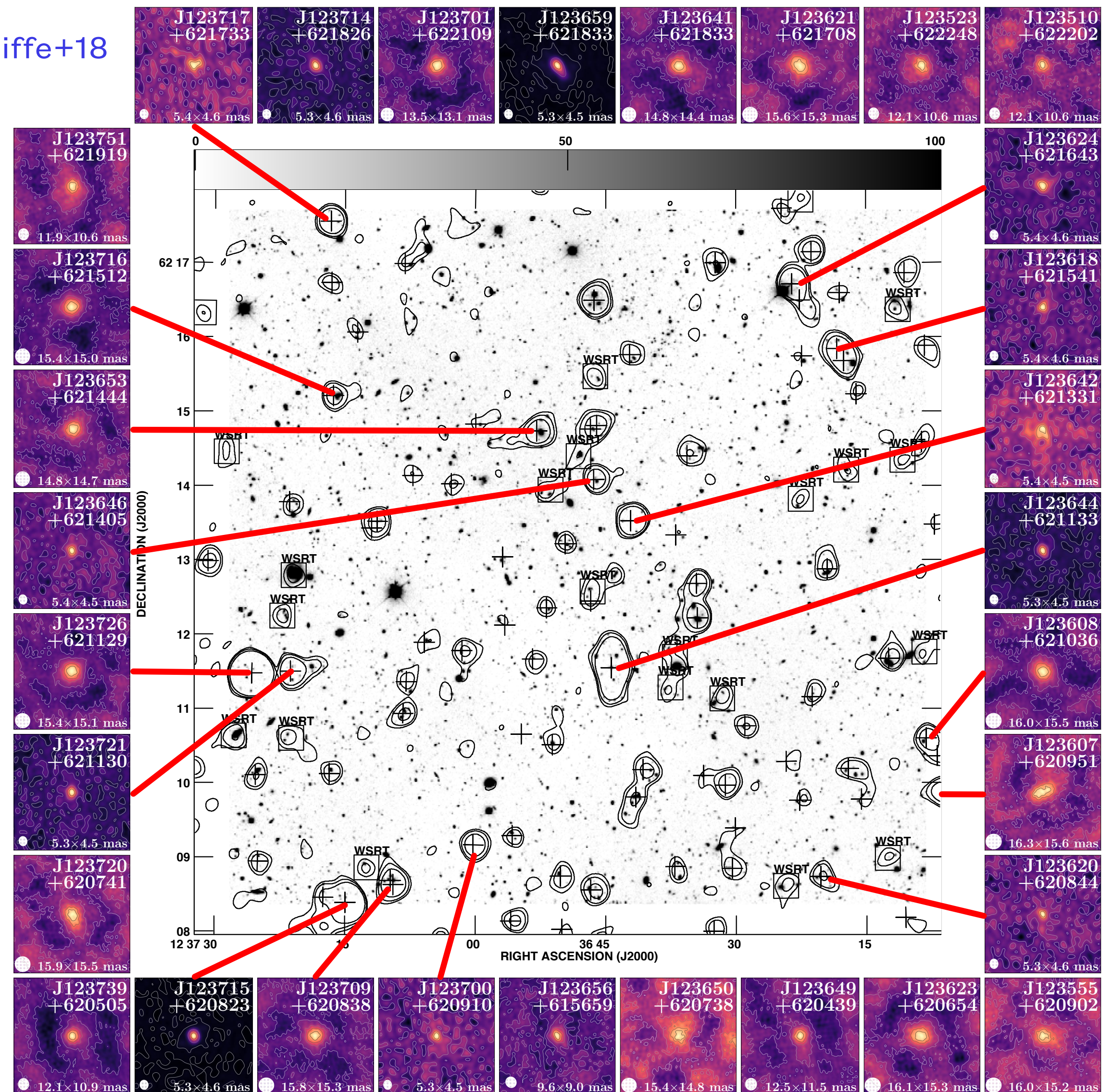


# And finally!

### Key takeaways

- Wide-field VLBI has many use cases and could be useful to your science.
- Calibration is simple and additional steps easily parallelised (and becoming user-friendly!)
- Additional calibration techniques applicable to standard VLBI observations e.g. MSSC.
- Final hurdle of primary beam correction of heterogeneous arrays currently being overcome.

Radcliffe+18





# THANKS TO OUR SPONSORS:

CASA  
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**JUMPING JIVE**  
Joint Institute for VLBI  
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